Communication Avoiding Algorithms in Plasma and Magma

Bilel Hadri, Hatem Ltaief, Emmanuel Agullo, Fengguang Song, and Jack Dongarra

University of Tennessee Oak Ridge National Laboratory

Potential System Architecture

Systems	2009	2018	Difference Today & 2018
System peak	2 Pflop/s	1 Eflop/s	O(1000)
Power	6 MW	~20 MW	
System memory	0.3 PB	32 - 64 PB [.03 Bytes/Flop]	O(100)
Node performance	125 GF	1,2 or 15TF	O(10) - O(100)
Node memory BW	25 GB/s	2 - 4TB/s [.002 Bytes/Flop] (0(100)
Node concurrency	12	O(1k) or 10k	O(100) - O(1000)
Total Node Interconnect BW	3.5 GB/s	200-400GB/s (1:4 or 1:8 from memory BW)	0(100)
System size (nodes)	18,700	O(100,000) or O(1M)	O(10) - O(100)
Total concurrency	225,000	O(billion) [O(10) to O(100) for latency hiding]	O(10,000)
Storage	15 PB	500-1000 PB (>10x system memory is min)	O(10) - O(100)
10	0.2 TB	60 TB/s (how long to drain the machine)	O(100)
MTTI	days	O(1 day)	- O(10)

Factors that Necessitate Redesign of Our Software

- Steepness of the ascent from terascale to petascale to exascale
- Extreme parallelism and hybrid design
 - Preparing for million/billion way parallelism
- Tightening memory/bandwidth bottleneck
 - Limits on power/clock speed implication on multicore
 - Reducing communication will become much more intense
 - Memory per core changes, byte-to-flop ratio will change
- Necessary Fault Tolerance
 - MTTF will drop
 - Checkpoint/restart has limitations



Average Number of Cores Per Supercomputer for Top20



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Major Changes to Software

- Must rethink the design of our software
 - Another disruptive technology
 - Similar to what happened with cluster computing and message passing
 - Rethink and rewrite the applications, algorithms, and software
- Numerical libraries for example will change
 - For example, both LAPACK and ScaLAPACK will undergo major changes to accommodate this

Parallel Linear Algebra Software for Multicore Architectures (PLASMA)



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Software/Algorithms follow hardware evolution in time					
LINPACK (70's) (Vector operations)		Rely on - Level-1 BLAS operations			
LAPACK (80's) (Blocking, cache friendly)		Rely on - Level-3 BLAS operations			
ScaLAPACK (90's) (Distributed Memory)		Rely on - PBLAS Mess Passing			
PLASMA (00's) New Algorithms (many-core friendly) Those new algorithms		Rely on - a DAG/scheduler - block data layout - some extra kernels			

- have a very low granularity, they scale very well (multicore, petascale computing, ...)

- removes a lots of dependencies among the tasks, (multicore, distributed computing)
- avoid latency (distributed computing, out-of-core)
- rely on fast kernels

Those new algorithms need new kernels and rely on efficient scheduling algorithms.

QR Factorization Intel 16 cores Tall Skinny Matrices



M=51200 x N

9





Fork-join, bulk synchronous processing



Parallel Tasks in QR



 Break into smaller tasks and remove dependencies











Step 2: Use R to zero A_{1,2}





Step 2: Use R to zero A_{1,2}





Step 2: Use R to zero A_{1,2}

Step3: Use R to zero A_{1,3}





Step 2: Use R to zero A_{1,2}

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Step 2: Use R to zero A_{1,2}

Step3: Use R to zero A_{1.3}

QR Factorization Intel 16 cores Tall Skinny Matrices



M=51200 x N

18

PLASMA: Parallel Linear Algebra s/w for Multicore Architectures

•Objectives

- high utilization of each core
- scaling to large number of cores
- shared or distributed memory

Methodology

- DAG scheduling
- explicit parallelism
- implicit communication
- Fine granularity / block data layout

Arbitrary DAG with dynamic scheduling



Time

Tile QR factorization



Fork-join parallelism

Communication Avoiding Algorithms

- Goal: Algorithms that communicate as little as possible
- Jim Demmel and company have been working on algorithms that obtain a provable minimum communication.
- Direct methods (BLAS, LU, QR, SVD, other decompositions)
 - Communication lower bounds for *all* these problems
 - Algorithms that attain them (*all* dense linear algebra, some sparse)
 - Mostly not in LAPACK or ScaLAPACK (yet)
- Iterative methods Krylov subspace methods for Ax=b, $Ax=\lambda x$
 - Communication lower bounds, and algorithms that attain them (depending on sparsity structure)
 - Not in any libraries (yet)
- For QR Factorization they can show:



MT=6 and NT=3
split into 2 domains
3 overlapped steps
panel factorization
updating the trailing submatrix
merge the domains

TS matrix



August 28, 2009



TS matrix > MT=6 and NT=3

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3 overlapped steps

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- > merge the domains
- Final R computed





Example with 4 and 8 Domains





A. Pothen and P. Raghavan. Distributed orthogonal factorization. In *The 3rd Conference on Hypercube Concurrent Computers and Applications, volume II, Applications,* pages 1610–1620, Pasadena, CA, Jan. 1988. ACM. Penn. State.



Execution Trace



Fig. 11. Parallel execution traces of SP-16 with MT=32 and NT=4 on 8 cores.

TABLE III

IMPROVEMENT OF SP-CAQR AGAINST OTHER LIBRARIES (PERFORMANCE RATIO).

Matrix sizes	PLASMA	MKL	ScaLAPACK	LAPACK
51200 - 200	9.54	8.77	3.38	28.63
51200 - 3200	1.27	4.10	2.88	11.05







QR Factorization Intel 16 cores Tall Skinny Matrices



M=51200 x N

Gflop/s

39



- grig.sinrg.cs.utk.edu
- 61 nodes
 - Two CPUs per node
 - Intel Xeon 3.20GHz
 - Peak performance 6.4 GFLOPS
 - Myrinet interconnection (MX 1.0.0)
- Goto BLAS 1.26
 - DGEMM performance 5.57 GFLOPS (87%)
- MPICH-MX
- gcc 64 bits



Weak Scalability of CAQR on the Grig Cluster





Weak Scalability of CAQR on the Grig Cluster





Weak Scalability of CAQR on the Grig Cluster





Scalability of CAQR on the Grig Cluster (8 tiles per row) peak dgemm Distri. CAQR ScaLAPACK **GFLOPS** per Core Number of Cores



- Architectural trends are forcing major changes to our algorithms
- Communication avoiding algorithms will be critical for performance.
- PLASMA and MAGMA will make use of CA algorithms.