

An Extended Set of FORTRAN Basic Linear Algebra Subprograms

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This paper describes an extension to the set of Basic Linear Algebra Subprograms. The extensions are targeted at matrix-vector operations that should provide for efficient and portable implementations of algorithms for high-performance computers.

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1. INTRODUCTION

In 1973, Hanson, Krogh, and Lawson [9] described the advantages of adopting a set of basic routines for problems in linear algebra. The original basic linear algebra subprograms, now commonly referred to as the BLAS and fully described by Lawson, Hanson, Kincaid, and Krogh [11, 12], have been very successful and used in a wide range of software including LINPACK [5] and many of the algorithms published in *ACM Transactions on Mathematical Software*. In particular, they are an aid to clarity, portability, modularity, and maintenance of

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software, and have become a de facto standard for the elementary vector operations. An excellent discussion of the *raison d'être* of the BLAS is given by Dodson and Lewis [1].

Special versions of the BLAS, in some cases machine code versions, have been implemented on a number of computers, thus improving the efficiency of the BLAS. Nevertheless, with some modern machine architectures, the use of the BLAS is not the best way to improve the efficiency of higher level codes. On vector machines, for example, one needs to optimize at least at the level of matrix-vector operations in order to approach the potential efficiency of the machine (see [2] and [3]); the use of BLAS inhibits this optimization because they hide the matrix-vector nature of the operations from the compiler.

We believe the time is right to specify an additional set of BLAS designed for matrix-vector operations. It has been our experience that a small set of matrix-vector operations occurs frequently in the implementation of many of the most common algorithms in linear algebra. We define here the basic operations for that set, together with the naming conventions and calling sequences. Routines at this level should provide a reasonable compromise between the sometimes conflicting aims of efficiency and modularity, and it is our hope that efficient implementations will become available on a wide range of computer architectures.

During the Gatlinburg meeting of June 1984 (Waterloo, Ontario), discussions among the participants encouraged us to prepare a proposed set of Level 2 BLAS. At about the same time, IFIP Working Group 2.5 started a project on the same subject at their annual meeting in Pasadena, California.

An initial proposal was drafted and presented at the "Parvec IV Workshop" held at Purdue University, Lafayette, Indiana, October 29-30, 1984. A series of meetings was planned so that the project would reflect the best thinking of the mathematical software community. Four meetings soliciting input were held. These occurred at SIAM conferences: the "Spring Meeting of the Society" (Seattle, Washington, July 16-20, 1984), the "Conference on Applied Linear Algebra" (Raleigh, North Carolina, April 29-May 2, 1985), the "Fall Meeting of the Society" (Tempe, Arizona, October 28-30, 1985), and the "Conference on Parallel Processing for Scientific Computing" (Norfolk, Virginia, November 18-21, 1985). In addition, we had discussions with the ACM-SIGNUM Board at the board meeting in Seattle, Washington, in July 1984.

Earlier, a modified proposal was printed in *SIGNUM Newsletter* [6]. In that document we invited readers to send us their views and suggestions for changes to the design of the extended BLAS. Thus, we have appealed to a wide audience within the mathematical software community. Our hope is that the proposed set of routines that constitute the extended BLAS will find wide application in future software for numerical linear algebra and provide a useful tool for implementors and users.

In this paper we refer to the existing BLAS of Lawson et al. as *Level 1 BLAS*, and the new extended set as *Level 2 BLAS*. Level 2 BLAS involve $O(mn)$ scalar operations, where m and n are the dimensions of the matrix involved. These could be programmed by a series of calls to Level 1 BLAS, though we do not recommend that they be implemented in that way. Hence, in a natural sense, Level 2 BLAS are performing basic operations at one level higher than Level 1 BLAS.

In [7] we present a model implementation of the Level 2 BLAS in FORTRAN 77 (extended to include a COMPLEX*16 data type), and also a set of rigorous test programs.

2. SCOPE OF THE LEVEL 2 BLAS

The following three types of basic operation are performed by the Level 2 BLAS:

- (1) matrix-vector products of the form

$$y \leftarrow \alpha Ax + \beta y, \quad y \leftarrow \alpha A^T x + \beta y, \quad \text{and} \quad y \leftarrow \alpha \bar{A}^T x + \beta y,$$

where α and β are scalars, x and y are vectors, and A is a matrix; and

$$x \leftarrow Tx, \quad x \leftarrow T^T x, \quad \text{and} \quad x \leftarrow \bar{T}^T x,$$

where x is a vector and T is an upper or lower triangular matrix.

- (2) rank-one and rank-two updates of the form

$$A \leftarrow \alpha xy^T + A, \quad A \leftarrow \alpha x\bar{y}^T + A, \quad H \leftarrow \alpha x\bar{x}^T + H, \quad \text{and} \\ H \leftarrow \alpha x\bar{y}^T + \bar{\alpha} y\bar{x}^T + H,$$

where H is a Hermitian matrix.

- (3) solution of triangular equations of the form

$$x \leftarrow T^{-1}x, \quad x \leftarrow T^{-T}x, \quad \text{and} \quad x \leftarrow \bar{T}^{-T}x,$$

where T is a nonsingular upper or lower triangular matrix.

Where appropriate, the operations are applied to general, general band, Hermitian, Hermitian band, triangular, and triangular band matrices in both real and complex arithmetic, and in single and double precision.

In Appendix B we propose corresponding sets of routines in which the internal computation is performed in extended precision, and the vectors x and/or y are stored in extended precision, so that the extra internal precision is not all discarded on return from the routine. This proposal is aimed at environments that support extended-precision arithmetic, for example, machines performing IEEE arithmetic [10]. We propose these routines as an optional extension to the Level 2 BLAS because it is not possible to specify a complete set within the confines of ANSI FORTRAN 77. The only case that can be realized within the standard is where the matrix is real single precision and the extended-precision vectors are real double precision. Code for these routines is not included in [7].

3. NAMING CONVENTIONS

The name of a Level 2 BLAS is in the LINPACK style and consists of five characters, the last of which may be blank. The first character in the name denotes the FORTRAN data type of the matrix, as follows:

- S REAL,
 D DOUBLE PRECISION,
 C COMPLEX, and
 Z COMPLEX*16 or DOUBLE COMPLEX (if available).

Table I. Names of the Level 2 BLAS

COMPLEX	REAL	MV	R	R2	SV
CGE	SGE	*	*		
CGB	SGB	*			
CHE	SSY	*	*	*	
CHP	SSP	*	*	*	
CHB	SSB	*			
CTR	STR	*			*
CTP	STP	*			*
CTB	STB	*			*

Characters two and three in the name denote the kind of matrix involved, as follows:

- GE general matrix,
- GB general band matrix,
- HE Hermitian matrix,
- SY symmetric matrix,
- HP Hermitian matrix stored in packed form,
- SP symmetric matrix stored in packed form,
- HB Hermitian band matrix,
- SB symmetric band matrix,
- TR triangular matrix,
- TP triangular matrix stored in packed form, and
- TB triangular band matrix.

The fourth and fifth characters in the name denote the type of operation, as follows:

- MV matrix-vector product,
- R rank-one update,
- R2 rank-two update, and
- SV solving a system of linear equations.

The available combinations are indicated in Table I. In the first column, under "COMPLEX," the initial C may be replaced by Z. In the second column, under "REAL," the initial S may be replaced by D. See Appendix C for the full subroutine calling sequences.

The collection of routines can be thought of as being divided into four separate parts: REAL, DOUBLE PRECISION, COMPLEX, and COMPLEX*16. The routines can be written in ANSI standard FORTRAN 77, with the exception of the routines that use COMPLEX*16 variables. These routines are included for completeness and for their usefulness on those systems that support this data type, but because they do not conform to the FORTRAN standard, they may not be available on all machines.

For the general rank-1 update (GER), we specify two complex routines: CGERC for $A \leftarrow \alpha xy^T + A$ and CGERU for $A \leftarrow \alpha xy^T + A$. This is the only exception to the one-to-one correspondence between REAL and COMPLEX routines. See Section 7 for further discussion.

We do not specify routines for rank-1 and rank-2 updates applied to band matrices, because these can be obtained by calls to the rank-1 and rank-2 full matrix routines. This is illustrated in Appendix A.

4. ARGUMENT CONVENTIONS

We follow a convention for the argument lists similar to that for the Level 1 BLAS, but with extensions where comparable arguments are not present in the Level 1 BLAS. The order of the arguments is as follows:

- (1) arguments specifying options,
- (2) arguments defining the size of the matrix,
- (3) input scalar,
- (4) description of the input matrix,
- (5) description of input vector(s),
- (6) input scalar (associated with the input/output vector),
- (7) description of the input/output vector, and
- (8) description of the input/output matrix.

Note that not each category is present in each of the routines.

The arguments that specify options are character arguments with the names *TRANS*, *UPLO*, and *DIAG*. *TRANS* is used by the matrix-vector product routines, as shown in Table II. In the REAL case, the values 'T' and 'C' have the same meaning.

UPLO is used by the Hermitian, symmetric, and triangular matrix routines to specify whether the upper or lower triangle is being referenced, as shown in Table III.

DIAG is used by the triangular matrix routines to specify whether or not the matrix is unit triangular, as shown in Table IV. When *DIAG* is supplied as 'U', the diagonal elements are not referenced.

We recommend that the corresponding lowercase characters be accepted with the same meaning, although, because they are not included in the standard FORTRAN character set, their use may not be supported on all systems. See Section 7 for further discussion.

It is worth noting that actual character arguments in FORTRAN may be longer than the corresponding dummy arguments. Therefore, for example, the value 'T' for *TRANS* may be passed as *TRANSPOSE*.

The size of the matrix is determined by the arguments *M* and *N* for an *m*-by-*n* rectangular matrix, and by the argument *N* for an *n*-by-*n* symmetric, Hermitian, or triangular matrix. Note that it is permissible to call the routines with *M* or *N* = 0, in which case the routines exit immediately without referencing their vector or matrix arguments. The bandwidth is determined by the arguments *KL* and *KU* for a rectangular matrix with *kl* subdiagonals and *ku* superdiagonals, respectively; and by the argument *K* for a symmetric, Hermitian, or triangular matrix with *k* subdiagonals and/or superdiagonals.

The description of the matrix consists of either the array name (*A*) followed by the leading dimension of the array (*LDA*) as declared in the calling (sub)program, when the matrix is being stored in a two-dimensional array; or the

Table II. Meaning of TRANS

Value	Meaning
'N'	Operate with the matrix
'T'	Operate with the transpose of the matrix
'C'	Operate with the conjugate transpose of the matrix

Table III. Meaning of UPLO

Value	Meaning
'U'	Upper triangle
'L'	Lower triangle

Table IV. Meaning of DIAG

Value	Meaning
'U'	Unit triangular
'N'	Nonunit triangular

array name (AP) alone when the matrix is being stored in packed form in a one-dimensional array. In the former case, the actual array must contain at least $((n-1)d + l)$ elements, where d is the leading dimension of the array, $d \geq l$, and $l = m$ for the GE routines, $l = n$ for the SY, HE, and TR routines, $l = kl + ku + 1$ for the GB routines, and $l = k + 1$ for the SB, HB, or TB routines. For packed storage the actual array must contain at least $n(n+1)/2$ elements.

The scalars always have the dummy argument names *ALPHA* and *BETA*.

As with the existing BLAS, the description of a vector consists of the name of the array (X or Y) followed by the storage spacing (increment) in the array of the vector elements (*INCX* or *INCY*). The increment is allowed to be positive or negative, but not 0 (see Section 7). When the vector x consists of k elements, the corresponding actual array argument X must be of length at least $(1 + (k-1)|INCX|)$. For those routines that include the argument *BETA*, when *BETA* is supplied as 0, the array Y need not be set on input, so that operations such as $y \leftarrow \alpha Ax$ may be performed without initially setting y to 0.

Note that the MV routines must not be called with the dummy arguments X and Y associated with the same actual argument. (Such association is not supported by the model implementation and would also contravene the FORTRAN standard.)

The following values of arguments are invalid.

Any value of the character arguments *DIAG*, *TRANS*, or *UPLO* whose meaning is not specified is;

$M < 0$;

$N < 0$;

$KL < 0$;

$KU < 0$;

$K < 0$;

$LDA < \max(1, M)$ for the GE routines;
 $LDA < KL + KU + 1$ for the GB routines;
 $LDA < N$ for the HE, SY, and TR routines;
 $LDA < K + 1$ for the HB, SB, and TB routines;
 $INCX = 0$; and
 $INCY = 0$.

If a routine is called with an invalid value for any of its arguments, then it must report the fact and terminate execution of the program. In the model implementation (see [7]), each routine, on detecting an error, calls a common error-handling routine XERBLA, passing to it the name of the routine and the number of the first argument that is in error. Specialized implementations may call system-specific exception-handling and diagnostic facilities, either via an auxiliary routine XERBLA or directly from the routines. One advantage of using XERBLA is that the test program can then test that all errors are detected (see [7]).

5. STORAGE CONVENTIONS

Unless otherwise stated it is assumed that matrices are stored conventionally in a two-dimensional array with matrix element a_{ij} stored in array element $A(I, J)$.

The routines for real symmetric and complex Hermitian matrices allow for the matrix either to be stored in the upper ($UPLO = 'U'$) or lower ($UPLO = 'L'$) triangle of a two-dimensional array, or to be packed in a one-dimensional array. In the latter case, the upper triangle may be packed sequentially column by column ($UPLO = 'U'$), or the lower triangle may be packed sequentially column by column ($UPLO = 'L'$). Note that for real symmetric matrices packing the upper triangle by columns is equivalent to packing the lower triangle by rows, and packing the lower triangle by columns is equivalent to packing the upper triangle by rows. (For complex Hermitian matrices, the only difference is that the off-diagonal elements are conjugated.)

For triangular matrices the argument $UPLO$ serves to define whether the matrix is upper ($UPLO = 'U'$) or lower ($UPLO = 'L'$) triangular. In packed storage the triangle has to be packed by column.

The band matrix routines allow storage in the same style as with LINPACK, so that the j th column of the matrix is stored in the j th column of the FORTRAN array. For a general band matrix, the diagonal of the matrix is stored in row $ku + 1$ of the array. For a Hermitian or symmetric matrix, either the upper triangle ($UPLO = 'U'$) may be stored, in which case the leading diagonal is in row $k + 1$ of the array, or the lower triangle ($UPLO = 'L'$) may be stored, in which case the leading diagonal is in the first row of the array. For an upper triangular band matrix ($UPLO = 'U'$), the leading diagonal is in row $k + 1$ of the array, and for a lower triangular band matrix ($UPLO = 'L'$), the leading diagonal is in the first row.

For a Hermitian matrix, the imaginary parts of the diagonal elements are of course 0, and thus the imaginary parts of the corresponding FORTRAN array elements need not be set, but are assumed to be 0. In the R and R2 routines,

these imaginary parts will be set to 0 on return, except when $\alpha = 0$, in which case the routines exit immediately.

For packed triangular matrices, the same storage layout is used whether or not $DIAG = 'U'$; that is, space is left for the diagonal elements even if those array elements are not referenced.

6. SPECIFICATION OF THE LEVEL 2 BLAS

Type and dimension for variables occurring in the subroutine specifications are as follows:

INTEGER INCX, INCY, K, KL, KU, LDA, M, N
 CHARACTER*1 DIAG, TRANS, UPLO

For routines whose first letter is S:

REAL ALPHA, BETA
 REAL X(*), Y(*)
 REAL A(LDA, *)
 REAL AP(*)

For routines whose first letter is D:

DOUBLE PRECISION ALPHA, BETA
 DOUBLE PRECISION X(*), Y(*)
 DOUBLE PRECISION A(LDA, *)
 DOUBLE PRECISION AP(*)

For routines whose first letter is C:

COMPLEX ALPHA
 COMPLEX BETA
 COMPLEX X(*), Y(*)
 COMPLEX A(LDA, *)
 COMPLEX AP(*)

Except that for CHER and CHPR the scalar α is REAL, so that the first declaration above is replaced by

REAL ALPHA

For routines whose first letter is Z, one of the alternative (nonstandard) specifications is:

COMPLEX*16	ALPHA	DOUBLE COMPLEX	ALPHA
COMPLEX*16	BETA	DOUBLE COMPLEX	BETA
COMPLEX*16	X(*), Y(*)	DOUBLE COMPLEX	X(*), Y(*)
COMPLEX*16	A(LDA, *)	DOUBLE COMPLEX	A(LDA, *)
COMPLEX*16	AP(*)	DOUBLE COMPLEX	AP(*)

except that for ZHER and ZHPR the first declaration above is replaced by

DOUBLE PRECISION ALPHA

The generic names, argument lists, and specifications for the extended BLAS now follow. Refer to Table I for the specific subroutine names.

In the following argument lists, the array name *AP* is used for the cases where the matrix *A* is supplied in packed form; in all other cases, the array name *A* is used:

(1) *General matrix vector products.*

For a general matrix,

_GEMV(TRANS, M, N, ALPHA, A, LDA, X, INCX, BETA, Y, INCY)

for a general band matrix,

_GBMV(TRANS, M, N, KL, KU, ALPHA, A, LDA, X, INCX, BETA, Y, INCY)

Operation:

if TRANS = 'N', $y \leftarrow \alpha Ax + \beta y$;

if TRANS = 'T', $y \leftarrow \alpha A^T x + \beta y$;

if TRANS = 'C', $y \leftarrow \alpha \bar{A}^T x + \beta y$.

(2) *Symmetric or Hermitian matrix vector products.*

For a symmetric or Hermitian matrix,

_SYMV(UPLO, N, ALPHA, A, LDA, X, INCX, BETA, Y, INCY)

_HEMV(UPLO, N, ALPHA, A, LDA, X, INCX, BETA, Y, INCY)

for a symmetric or Hermitian matrix in packed storage,

_SPMV(UPLO, N, ALPHA, AP, X, INCX, BETA, Y, INCY)

_HPMV(UPLO, N, ALPHA, AP, X, INCX, BETA, Y, INCY)

for a symmetric or Hermitian band matrix,

_SBMV(UPLO, N, K, ALPHA, A, LDA, X, INCX, BETA, Y, INCY)

_HBMV(UPLO, N, K, ALPHA, A, LDA, X, INCX, BETA, Y, INCY)

Operation:

$$y \leftarrow \alpha Ax + \beta y.$$

(3) *Triangular matrix vector products.*

For a triangular matrix,

_TRMV(UPLO, TRANS, DIAG, N, A, LDA, X, INCX)

for a triangular matrix in packed storage,

_TPMV(UPLO, TRANS, DIAG, N, AP, X, INCX)

for a triangular band matrix,

_TBMV(UPLO, TRANS, DIAG, N, K, A, LDA, X, INCX)

Operation:

if TRANS = 'N', $x \leftarrow Ax$;

if TRANS = 'T', $x \leftarrow A^T x$;

if TRANS = 'C', $x \leftarrow \bar{A}^T x$.

(4) *Triangular equation solvers.*

For a triangular matrix,

_TRSV(UPLO, TRANS, DIAG, N, A, LDA, X, INCX)

for a triangular matrix in packed storage,

_TPSV(UPLO, TRANS, DIAG, N, AP, X, INCX)

for a triangular band matrix

_TBSV(UPLO, TRANS, DIAG, N, K, A, LDA, X, INCX)

Operation:

if $TRANS = 'N'$, $x \leftarrow A^{-1}x$;

if $TRANS = 'T'$, $x \leftarrow A^{-T}x$;

if $TRANS = 'C'$, $x \leftarrow \bar{A}^{-T}x$.

(5) *General rank-1 updates.*

For a general matrix,

GER(M, N, ALPHA, X, INCX, Y, INCY, A, LDA)

for real matrices,

SGER or DGER performs the operation $A \leftarrow \alpha xy^T + A$;

for complex matrices,

CGERC or ZGERC performs the operation $A \leftarrow \alpha x\bar{y}^T + A$, and

CGERU or ZGERU performs the operation $A \leftarrow \alpha xy^T + A$.

(6) *Symmetric or Hermitian rank-1 updates.*

For a symmetric or Hermitian matrix,

_SYR(UPLO, N, ALPHA, X, INCX, A, LDA)

_HER(UPLO, N, ALPHA, X, INCX, A, LDA)

for a symmetric or Hermitian matrix in packed storage,

_SPR(UPLO, N, ALPHA, X, INCX, AP)

_HPR(UPLO, N, ALPHA, X, INCX, AP)

Operation:

$$A \leftarrow \alpha x\bar{x}^T + A;$$

for real symmetric matrices, this is simply

$$A \leftarrow \alpha xx^T + A.$$

(7) *Symmetric or Hermitian rank-2 updates.*

For a symmetric or Hermitian matrix,

```
_SYR2(UPLO, N, ALPHA, X, INCX, Y, INCY, A, LDA)
_HER2(UPLO, N, ALPHA, X, INCX, Y, INCY, A, LDA)
```

for a symmetric or Hermitian matrix in packed storage,

```
_SPR2(UPLO, N, ALPHA, X, INCX, Y, INCY, AP)
_HPR2(UPLO, N, ALPHA, X, INCX, Y, INCY, AP)
```

Operation:

$$A \leftarrow \alpha xy^T + \bar{\alpha} yx^T + A;$$

for real symmetric matrices, this is simply

$$A \leftarrow \alpha xy^T + \alpha yx^T + A.$$

7. RATIONALE

The three basic matrix-vector operations chosen (Section 2) were obvious candidates because they occur in a wide range of linear algebra applications and occur at the innermost level of many algorithms. The hard decision was to restrict the scope only to these operations, since there are many other potential candidates such as matrix scaling and sequences of plane rotations. Similarly, we could have extended the scope by applying the operations to other types of matrices such as complex symmetric or augmented band matrices. We have aimed at a reasonable compromise between a much larger number of routines each performing one type of operation (e.g., $x \leftarrow L^{-T}x$), and a smaller number of routines with a more complicated set of options. There are in fact, in each precision, 16 real routines performing altogether 43 different operations, and 17 complex routines performing 58 different operations.

We feel that to extend the scope further would significantly reduce the chances of having the routines implemented efficiently over a wide range of machines, because it would place too heavy a burden on implementors. On the other hand, to restrict the scope further would place too narrow a limit on the potential applications of the Level 2 BLAS.

We have adhered to the conventions of the Level 1 BLAS in allowing an increment argument to be associated with each vector, so that a vector could, for example, be a row of a matrix. This increment may be negative, in which case the elements of the vectors are taken in reverse order. This affects the definition of the operation. For example, if $m = n = 3$ and *INCX* and *INCY* are both negative, the *_GEMV* routines with *TRANS* = 'N' perform the operation

$$\begin{pmatrix} y_3 \\ y_2 \\ y_1 \end{pmatrix} \leftarrow \alpha \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix} \begin{pmatrix} x_3 \\ x_2 \\ x_1 \end{pmatrix} + \beta \begin{pmatrix} y_3 \\ y_2 \\ y_1 \end{pmatrix}.$$

In contrast to the Level 1 BLAS, however, we do not allow *INCX* or *INCY* to be 0. This feature would have little usefulness, it would complicate

implementation of the routines on many vector machines, and when the associated vector is an output vector, its meaning is ambiguous.

As noted earlier, corresponding to the real routine SGER we specify two complex routines: CGERC (for $A \leftarrow \alpha xy^T + A$) and CGERU (for $A \leftarrow \alpha xy^T + A$). Both are frequently required. An alternative would be to provide a single complex routine CGER with an option argument; however, this argument would become redundant in the real routine SGER. Rather than have redundant arguments, or different argument lists for the real and complex routines, we have chosen two distinct complex routines; they are analogous to the Level 1 BLAS CDOTC ($c \leftarrow \bar{x}^T y$) and CDOTU ($c \leftarrow x^T y$).

Note that no check has been included for singularity, or near singularity, in the triangular equation-solving routines. The requirements for such a test depend on the application, and so we felt that this should not be included, but should instead be performed before calling the triangular solver.

On certain machines that do not use the ASCII sequence on all of their FORTRAN systems, lowercase characters may not exist, so that the innocent looking argument 't', passed through the argument TRANS for designating a transposed matrix, is not in the FORTRAN character set. Some UNIVAC systems do not have a lowercase representation using the "field data" character set. On the CDC NOS-2 system, a mechanism is provided for a full 128 ASCII character set by using pairs of 6-bit host characters for certain 7-bit ASCII characters. This means that there is a two-for-one physical extension of the logical records that contain lowercase letters. This fact can hamper portability of codes written on ASCII machines that are later moved to CDC systems. The only safe way to proceed is to convert the transported text entirely into the FORTRAN character set. On the other hand, we believe that users on ASCII character set systems may wish to treat upper- and lowercase letters as equivalent in meaning. If this is done, it means that text that will be transported to machines of unknown types must have the ASCII set mapped into the FORTRAN character set before the text is moved.

The band storage scheme used by the GB, HB, SB, and TB routines has columns of the matrix stored in columns of the array, and diagonals of the matrix stored in rows of the array. This is the storage scheme used by LINPACK. An alternative scheme (used in some EISPACK routines [8, 13]) has rows of the matrix stored in rows of the array, and diagonals of the matrix stored in columns of the array. The latter scheme has the advantage that a band matrix-vector product of the form $y \leftarrow \alpha Ax + \beta y$ can be computed using long vectors (the diagonals of the matrix) stored in contiguous elements, and hence is much more efficient on some machines (e.g., CDC Cyber 205) than the first scheme. Other computations involving band matrices, however, such as $x \leftarrow Tx$, $x \leftarrow T^{-1}x$, and LU, and $U^T U$ factorization, cannot be organized "by diagonals"; instead, the computation sweeps along the band, and the LINPACK storage scheme has the advantage of reducing the number of page swaps and allowing contiguous vectors (the columns of the matrix) to be used.

We considered the possibility of generalizing the rank-1 and rank-2 updates to rank- k updates. Rank- k updates with $k > 1$ (but $k \ll n$) can achieve significantly better performance on some machines than rank-1 [4]. But to take advantage of

name	options	dim	b-width	scalar	matrix	x-vector	scalar	y-vector
_GEMV(TRANS,	M, N,		ALPHA, A,	LDA, X,	INCX,	BETA, Y,	INCY)
_GBMV(TRANS,	M, N, KL, KU,		ALPHA, A,	LDA, X,	INCX,	BETA, Y,	INCY)
_HEMV(UPLO,	N,		ALPHA, A,	LDA, X,	INCX,	BETA, Y,	INCY)
_HEMV(UPLO,	N,	K,	ALPHA, A,	LDA, X,	INCX,	BETA, Y,	INCY)
_HPMV(UPLO,	N,		ALPHA, AP,	X,	INCX,	BETA, Y,	INCY)
_SYMV(UPLO,	N,		ALPHA, A,	LDA, X,	INCX,	BETA, Y,	INCY)
_SBMV(UPLO,	N,	K,	ALPHA, A,	LDA, X,	INCX,	BETA, Y,	INCY)
_SBMV(UPLO,	N,		ALPHA, AP,	X,	INCX,	BETA, Y,	INCY)
_TRMV(UPLO, TRANS, DIAG,	N,		A,	LDA, X,	INCX)		
_TRMV(UPLO, TRANS, DIAG,	N,	K,	A,	LDA, X,	INCX)		
_TRMV(UPLO, TRANS, DIAG,	N,		AP,	X,	INCX)		
_TRSV(UPLO, TRANS, DIAG,	N,		A,	LDA, X,	INCX)		
_TRSV(UPLO, TRANS, DIAG,	N,	K,	A,	LDA, X,	INCX)		
_TRSV(UPLO, TRANS, DIAG,	N,		AP,	X,	INCX)		
name	options	dim	scalar	x-vector	y-vector	matrix		
GER(M, N,	ALPHA, X,	INCX,	Y,	INCY, A,	LDA)	
_HER(UPLO,	N,	ALPHA, X,	INCX,		A,	LDA)	
_HPR(UPLO,	N,	ALPHA, X,	INCX,		AP)		
_HER2(UPLO,	N,	ALPHA, X,	INCX,	Y,	INCY, A,	LDA)	
_HPR2(UPLO,	N,	ALPHA, X,	INCX,	Y,	INCY, AP)		
_SYR(UPLO,	N,	ALPHA, X,	INCX,		A,	LDA)	
_SPR(UPLO,	N,	ALPHA, X,	INCX,		AP)		
_SYR2(UPLO,	N,	ALPHA, X,	INCX,	Y,	INCY, A,	LDA)	
_SPR2(UPLO,	N,	ALPHA, X,	INCX,	Y,	INCY, AP)		

Fig. 1. Rank-1 update of a band matrix.

this usually requires complicating the calling algorithm; and moreover, rank- k updates with $k \approx n$ would allow an even higher level operation such as matrix multiplication "in by the back door." We prefer to keep to a clean concept of genuine matrix-vector operations.

APPENDIX A

In this appendix we illustrate how to use the full matrix update routines to obtain rank-1 and rank-2 updates to band matrices. We assume the vectors x and y are such that no fill-in occurs outside the band, in which case the update affects only a full rectangle within the band matrix A . This is illustrated in Figure 1 for the case where $m = n = 9$, $kl = 2$, $ku = 3$, and the update commences in row (and column) $l = 3$. We see that the update affects only that part of A indicated by the dotted lines, that is, the $(kl + 1)$ -by- $(ku + 1)$ part of A starting at a_{ll} .

The routines that we could have included are `_GBR`, `_SBR`, and `_SBR2` (in the complex case, `_HBR` and `_HBR2`). Their argument lists could have been

```
_GBR(M, N, KL, KU, L, ALPHA, X, INCX, Y, INCY, A, LDA)
_SBR(UPLO, N, K, L, ALPHA, X, INCX, A, LDA)
_SBR2(UPLO, N, K, L, ALPHA, X, INCX, Y, INCY, A, LDA)
```

where the argument L denotes the starting row and column for the update, and the elements x_i and y_i , of the vectors x and y , are in elements $X(1)$ and $Y(1)$ of the arrays X and Y .

Calls to `SGBR` can be achieved by

```
KM = MIN(KL + 1, M - L + 1)
KN = MIN(KU + 1, N - L + 1)
CALL SGER(KM, KN, ALPHA, X, INCX, Y, INCY, A(KU + 1, L),
          MAX(KM, LDA - 1))
```

Calls to `SSBR` can be achieved by

```
KN = MIN(K + 1, N - L + 1)
IF (UPLO .EQ. 'U') THEN
  CALL SSYR('U', KN, ALPHA, X, INCX, A(K + 1, L), MAX(1, LDA - 1))
ELSE
  CALL SSYR('L', KN, ALPHA, X, INCX, A(1, L), MAX(1, LDA - 1))
END IF;
```

and similarly for calls to `SSBR2`.

APPENDIX B

In this appendix we propose an additional set of real and complex Level 2 routines that allow extended-precision matrix-vector operations to be performed. The names of these routines are obtained by preceding the character representing the FORTRAN data type (S or C) by the character E. The matrix is always stored in working precision (which is single precision for the ES- and EC- set of routines, and double precision for the ED- and EZ- set). The computation must be performed in extended precision (which is more accurate than the working precision).

Such routines are useful, for example, in the accurate computation of residuals in iterative refinement. Many machines have extended-precision registers in which extended-precision computation is performed at little or no extra cost. In order to allow the additional precision to be carried through a series of calls to these routines, however, at least one, in some cases both, of the vectors x and y must be stored in extended precision.

These routines are to perform the operations described in Section 2 as follows:

For the matrix-vector operations,

$$y \leftarrow \alpha Ax + \beta y, \quad y \leftarrow \alpha A^T x + \beta y, \quad y \leftarrow \alpha \bar{A}^T x + \beta y,$$

α , β , A , and x are working precision, y is extended precision, and the computation of y is to be performed in extended precision.

For the triangular operations,

$$\begin{array}{lll} x \leftarrow Tx, & x \leftarrow T^T x, & x \leftarrow \bar{T}^T x, \\ x \leftarrow T^{-1} x, & x \leftarrow T^{-T} x, & x \leftarrow \bar{T}^{-T} x, \end{array}$$

T is working precision, x is extended precision, and the computation of x is to be performed in extended precision.

For the rank-1 and rank-2 updates,

$$\begin{array}{ll} A \leftarrow \alpha xy^T + A, & A \leftarrow \alpha \bar{y}^T x + A, \\ H \leftarrow \alpha x \bar{x}^T + H, & H \leftarrow \alpha \bar{y} \bar{x}^T + H, \end{array}$$

α , A , and H are working precision, x and y are extended precision, and the computation is to be performed in extended precision.

The precise nature of the extended-precision data type cannot be specified here. The amount of extra precision available will depend on the architecture of the machine and the compiler; whether this is sufficient will depend on the application. For the rest of this appendix, we assume double precision is used to implement extended precision in the ES and EC routines, and quadruple precision in the ED and EZ routines (note, however, that quadruple precision is not specified in IEEE arithmetic). Then the ES- set of routines can be called and implemented in standard FORTRAN 77. The EC- set requires the addition of a COMPLEX*16 data type, as does the basic Z- set, but can be used across a wide range of machines. The ED-set requires the addition of a REAL*16 (quadruple-precision REAL) data type, while the EC- set requires a COMPLEX*32 (quadruple-precision COMPLEX) data type; these data types are provided on some systems. We strongly recommend that, if implementors provide extended-precision routines using these data types, they adhere to the specifications described here, so that at least a limited degree of portability may be achieved.

To test thoroughly that extended precision is used as specified in the internal computations requires an extra degree of sophistication from the test program. For all these reasons, neither a model implementation of the extended-precision routines nor a test program for them has been included in [7]; code for the ES- and EC- sets of routines may be obtained from the authors.

The specifications of the arguments remain exactly as in Section 6 except for the following:

for ESGEMV, ESGBMV, ESSYMV, ESSBMV, ESSPMV, ESGER, ESSYR2, and ESSPR2,

DOUBLE PRECISION Y(*)

for the corresponding EC routines,

COMPLEX*16 Y(*) (or equivalent)

for the corresponding ED routines,

REAL*16 Y(*) (or equivalent)

for the corresponding EZ routines,

COMPLEX*32 Y(*) (or equivalent)

for ESTRMV, ESTBMV, ESTPMV, ESTRSV, ESTBSV, ESTPSV, ESGER, ESSYR, ESSPR, ESSYR2, and ESSPR2,

DOUBLE PRECISION X(*)

for the corresponding EC routines,

COMPLEX*16 X(*) (or equivalent)

for the corresponding ED routines,

REAL*16 X(*) (or equivalent)

for the corresponding EZ routines,

COMPLEX*32 X(*) (or equivalent)

APPENDIX C

This appendix contains the calling sequences for the Level 2 BLAS.

(* * * *) (0) (0 0 * * * * 0 0 0)
 (* * * *) (0)
 (* * | * * * * |) (*)
 (* | * * * * | *) (*)
 (* * * * * | * *) + (*)
 (* * * * *) (0)
 (* * * * *) (0)
 (* * * * *) (0)
 (* * * *) (0)

$$A + xy^T$$

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