

References

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DIAG is used by the trapezoidal **matrix** routines to specify whether or not the **matrix** is unit trapezoidal as follows:

| Value | Meaning |
|-------|----------------------|
| 'U' | Unit trapezoidal |
| 'N' | Non-unit trapezoidal |

When **DIAG** is supplied as 'U' the diagonal elements are not referenced or overwritten.

- N (Input) Length of vectors.
- X (Input) Vector of elements to be summed.
- Y (Output) Vector of results of summation.
- IDEST (Input) Index of process where result is to be accumulated.
- MSGID (Input) Identifier for this message.

Current BLACS routines:

Data Communication Routines:

```

_GESD ( M, N, A, LDA, IDEST, MSGID )
_GERV ( M, N, A, LDA, ISRC, MSGID )
_GEBC ( M, N, A, LDA, ISRC, MSGID )

_TRSD ( UPLO, DIAG, M, N, A, LDA, IDEST, MSGID )
_TRRV ( UPLO, DIAG, M, N, A, LDA, ISRC, MSGID )
_TRBC ( UPLO, DIAG, M, N, A, LDA, ISRC, MSGID )

```

Global Operations:

```

_GMAX ( N, X, Y, IY, IDEST, MSGID )
_GMIN ( N, X, Y, IY, IDEST, MSGID )
_GSUM ( N, X, Y, IDEST, MSGID )

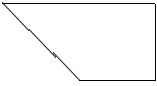
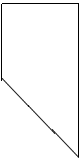
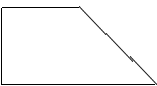
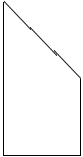
```

Trapezoidal matrices:

UPLO is used by the Hermitian, symmetric, and trapezoidal matrix routines to specify whether the upper or lower trapezoid is being referenced as follows:

| Value | Meaning |
|-------|-----------------|
| ‘U’ | Upper trapezoid |
| ‘L’ | Lower trapezoid |

The shape of the trapezoid to be sent is determined by M and N:

| UPLO | $M \leq N$ | $M > N$ |
|------|---|---|
| ‘U’ |  |  |
| ‘L’ |  |  |

Position Function

- type of data to be communicated:
(Integer, Single or Double precision, etc.)

ZZZ function of the routine:
(MAXimum, MINimum or SUM)

`_GMAX(N, X, Y, IY, IDEST, MSGID)`

Compare values of elements and produce the maximum(in absolute value?) (elementwise), i.e., for each $I=1, N$,

$$Y(I) = \max_{\text{allprocs}} X(I).$$

Parameters:

- N (Input) Length of vectors.
- X (Input) Vector of elements to be compared.
- Y (Output) Vector of results of comparison.
- IY (Output) Vector of indices of the processes that gave the maximum values.
- IDEST (Input) Index of process where result is to be accumulated.
- MSGID (Input) Identifier for this message.

`_GMIN(N, X, Y, IY, IDEST, MSGID)`

Compare values of elements and produce the minimum(in absolute value?) (elementwise), i.e., for each $I=1, N$,

$$Y(I) = \min_{\text{allprocs}} X(I).$$

Parameters:

- N (Input) Length of vectors.
- X (Input) Vector of elements to be compared.
- Y (Output) Vector of results of comparison.
- IY (Output) Vector of indices of the processes that gave the minimum values.
- IDEST (Input) Index of process where result is to be accumulated.
- MSGID (Input) Identifier for this message.

`_GSUM(N, X, Y, IDEST, MSGID)`

Sum the vector of elements.

Parameters:

- IDEST (Input) Index of destination process.
- MSGID (Input) Identifier for this message.

`_GERV(M, N, A, LDA, ISRC, MSGID)`

Receive array **A** from process **ISRC**.

`_TRRV(UPLO, DIAG, M, N, A, LDA, ISRC, MSGID)`

Receive trapezoidal array **A** from process **ISRC**.

Parameters :

- UPLO (Output) Specifies if the matrix is to be stored as a Lower or Upper trapezoidal matrix.
- DIAG (Output) Specifies whether or not the matrix is to be unit trapezoidal.
- M (Output) Row dimension of **A**.
- N (Output) Column dimension of **A**.
- A (Output) Array into which data is to be received.
- LDA (Input) Leading dimension of **A**.
- ISRC (Output) Index of source process.
- MSGID (Input) Identifier for this message.

`_GEBC(M, N, A, LDA, ISRC, MSGID)`

Send/receive matrix **A** to all processes from process with index **ISRC**.

`_TRBC(UPLO, DIAG, M, N, A, LDA, ISRC, MSGID)`

Send/receive trapezoidal matrix **A** to all processes from process with index **ISRC**.

Parameters :

- UPLO (Input/Output) Specifies if the matrix is stored as a Lower or Upper trapezoidal matrix.
- DIAG (Input/Output) Specifies whether or not the matrix is unit trapezoidal.
- M (Input/Output) Row dimension of **A**.
- N (Input/Output) Column dimension of **A**.
- A (Input/Output) Array of data to be sent/array into which data is to be received.
- LDA (Input) Leading dimension of **A**. $LDA \geq M$
- ISRC (Input/Output) Index of source process.
- MSGID (Input) Identifier for this message.

Global Operators :

General form `_GZZZ`

Appendix: “White Paper” Describing the BLACS

The BLACS are a set of communication routines that complement the level 1, 2 and 3 BLAS. The BLACS should provide tools for the implementation of numerical algorithms in linear algebra on distributed memory MIMD computers. The proposed routines cover the following operations:

- Point-to-point send/receive
- Broadcast
- Probe
- Global maximum, minimum and summation.

The naming convention is similar to the Level 2 and 3 BLAS.

Naming conventions: All names of BLACS subroutines are specified by at most six letters and are of the form `_XXYY` or `_GZZZ`.

Data Communication Routines:

General form `_XXYY`

Position Function

- type of data to be communicated:
(Integer, Single or Double precision, etc.)
- XX data structure:
(General or Trapezoidal)
- YY function of the routine:
(SenD, ReciVe, or BoadCast)

| |
|--|
| <code>_GESD(M, N, A, LDA, IDEST, MSGID)</code> |
|--|

Send matrix A to process IDEST.

| |
|--|
| <code>_TRSD(UPLO, DIAG, M, N, A, LDA, IDEST, MSGID)</code> |
|--|

Send trapezoidal matrix A to process IDEST.

Parameters:

- **UPLO** (Input) Specifies if the matrix is stored as a Lower or Upper trapezoidal matrix.
- **DIAG** (Input) Specifies whether or not the matrix is unit trapezoidal.
- **M** (Input) Row dimension of A.
- **N** (Input) Column dimension of A.
- **A** (Input) Array of data to be sent.
- **LDA** (Input) Leading dimension of A. $LDA \geq M$

3. I is fixed; N , $p = O(N^{1/2})$ and $M = O(N^{1/2})$ are increasing. Here we increase the number of processors and memory size proportionally to the matrix dimension n . This corresponds to laying out a fixed number of columns per memory.
4. N and M are fixed; I and $p = O(I)$ are increasing. Here we add more simultaneous independent problems as the number of processors grows.

- How portable should the codes be?

Is it acceptable to have one set of codes for SIMD and one for MIMD machines? One set of codes for machines requiring explicit message passing and another for codes not requiring this? LAPACK is quite large, and we would like to avoid writing and maintaining different versions. Can we use facilities like the C preprocessors or other macro packages to make porting easier, or do we want to maintain the current "pure source code portability" model? We have already sacrificed this to some extent by assuming the BLAS are machine dependent, as well as certain tuning parameters, so perhaps we should take advantage of limited machine dependency elsewhere. Other issues include noninterference with the rest of the application (e.g., not assuming all processors are available to be dedicated to this problem assuming multi programming of the nodes, not using global names for message IDs which may overlap with others).

- How soon should the BLACS and LAPACK code be developed?

LAPACK is being designed now for distributed memory machines and needs a package like the BLACS. There is a great deal of activity both in designing new architectures as well as software systems (as evidenced by the presentations at this meeting). So while it might seem reasonable to wait and see which systems come out on top, we cannot afford to wait too long because people need to use this code. Furthermore, our experience in writing the code will help decide which systems should come out on top. We should try to avoid features in the BLACS that prevent them from being emulated by other lower level software.

It was agreed that the following steps be taken:

1. Obtain a reasonable consensus among those people actively interested in the area. This workshop is one step in the process.
2. It is too early to focus on a proposal at this time.
3. Another workshop was needed to bring out ideas. Perhaps in the Fall would be the right time frame. The Cornell people have volunteered to host the next meeting.
4. Examples of LU decomposition (and perhaps other routines) using the proposed BLACS as well as alternate systems would be desirable, both to compare for ease of expression and performance.

6 Discussion

Jim Demmel lead a discussion in the final session. What follows summarizes the points brought out during that session.

- What linear algebra functions should the BLACS support?

This will depend upon the intended users of the BLACS more than anything else. If the BLACS are to be used for all applications, then a wider set of functions will have to be included.

- Which target machines should be supported?

The machines fall into several types depending on whether they are SIMD or MIMD, and whether the memory is distributed or not, with the distributed memory machines being the ones of most immediate interest. Sometimes underlying message passing systems differ as to whether they are blocking or nonblocking, etc., as well. The package could be designed to work with both SIMD and MIMD models, however this may complicate the situation. For example, a code written in a language like Fortran D will look significantly different than one doing explicit message passing.

- Which data layouts should be supported?

This is the most frequently asked question. There are clearly a great many more layouts possible than in LAPACK I, because of distributed memories of various sizes per processor, as well as the desire by some to support “multiple instance” routines, i.e., multiple independent input matrices describing independent problems. If these are laid out in separate memories, or “transposed” with part of each matrix in each memory, completely different algorithms might be needed. In addition, the user may only use some of the processors, or have his own special layout.

- How should performance scale?

There are several different ways to scale problems. The efficiency E is a function of the input problem size $N = n$ ($n =$ matrix dimension), the number of processors p , the memory per processor M , and the number of problem instances I . Scaling essentially means letting N , n , M and I grow in certain regimes without the efficiency E getting too low. Getting too low means being less than half as fast as a routine coded specifically for the machine. The following regimes are natural ones to consider trying to support:

1. M and I are fixed; p and $N = O(p)$ are increasing. In other words, we add processors and increase the problem size proportionately. Since M is fixed, for large enough p this means that each memory has at most a subblock of the matrix, not even a full column.
2. p and I are fixed; M and $N = O(M)$ are increasing. Here we increase the problem size as the memory grows. This corresponds to each memory storing a fixed fraction $1/p$ of the matrix.

Alan gave a personal perspective of the situation. Manufacturers of supercomputers are often slow to give users hands-on access to the underlying networks. Perhaps this is an appropriate strategy for them; their economic base consists of computational scientists, not computer scientists. It is our responsibility to decide what kinds of access to the networks we really want and need. At the very least, it is our responsibility to identify the communications routines that need to run fast on advanced architectures.

He also made the following remarks:

- SIMD/MM is not an issue. Synchronous/Asynchronous and Pipelining/Not Pipelining with arithmetic are issues.
- Not overlapping can cause the loss of at most a factor of 2, but makes programming portable. Without overlap, programs for LU factorization on all the machines can be made to look very much identical.
- A challenge (that is worth some thought) is whether overlapping of communication and arithmetic can be performed with a clean programming primitive.
- Subroutine names should be readable. The days of R2D2/C3PO are gone.
- Nearly all dense linear algebra programs on all machines use column (and/or row) wrapping. Thus, only parameters for row and column block sizes vary from machine to machine.
- Higher level abstractions can be illustrated with the idea of a column broadcast of column 1. It ought to look something like

```
SPREAD(A(:,1))
```

and should not depend on processor numbers or even whether the first columns of a matrix is in one or many processors. The software (person who writes the BLACS program) should figure out where the data must be sent and how it is to get there.

- Communications routines to perform matrix transpose (usually based on all-to-all personalized communication ideas) and matrix multiply steps (usually based on all-to-all broadcasting) are further needed.

Lennart Johnsson talked about the programming model used on the CM2. He wants the communication primitives to work on arrays independent of the data layout. A number of CMSL (CMS Scientific Subroutine Library) routines performing the following operations were described:

- All-to-all broadcast
- Global reduction
- Matrix-vector multiply
- Matrix-matrix multiply

with data decomposition specifications; it can be viewed as a language for programming “data-parallel problems” that can be mapped efficiently onto different machine architectures, including both SIMD and MIMD distributed-memory machines.

Fortran D supports two levels of data decomposition—fine-grain problem mapping induced by the structure of the underlying computation, and coarse-grain machine mapping caused by translating the problem onto the finite resources of the machines. Data decompositions are specified using `DECOMPOSITION`, `ALIGN` and `DISTRIBUTE` statements, as shown in the following example.

```
REAL X(100,100)
DECOMPOSITION A(100,100)
ALIGN X(I,J) WITH A(I+1,J-1)
DISTRIBUTE A(BLOCK, *)
DISTRIBUTE A(*, CYCLIC)
```

Some of the other features of Fortran D include:

- Static and dynamic data decompositions
- Regular and irregular data decompositions
- Deterministic program semantics
- Support for reduction operations.

The goal of Fortran D is to ease the task of developing efficient parallel programs. Users do not need to explicitly insert parallel constructs, synchronization, or communications. Instead, the Fortran D compiler uses the data decomposition to automatically convert programs into single-program multiple-data (SPMD) form with explicit message-passing. These node programs may take advantage of communications libraries such as Express or BLACS for efficient collective communications.

The data decomposition specifications in Fortran D are compatible with both Fortran 77 and Fortran 90. Researchers at Rice are developing the Fortran 77D compiler; the Fortran 90D compiler is being constructed at Syracuse. The Fortran D programming system includes a prototype compiler, automatic data partitioner, and static performance estimator. It is being developed in the context of the ParaScope parallel programming environment. Initial targets are the Intel iPSC/860 and Delta. It is planned that the Fortran 77/90D compiler will be optimized for matrix algebra.

5 Other SIMD models

Alan Edelman and Lennart Johnsson spoke on an approach to the BLACS from the perspective of the CM. They both felt that the BLACS, as proposed by van de Geijn, is at too low a level of abstraction and feel that a higher level is called for.

- Keep overheads low by utilizing advances in software technology—e.g., C macros, compiler in-line expansion
- Recognize existence of multiple application languages (C and Fortran-90, . . .)
- Use a readable naming convention.

In addition, Zipline will support PCL and other major protocols.

3.3 White paper on BLACS

Robert van de Geijn presented a “white paper” proposal for the BLACS. As described, the BLACS * are a set of communication routines that complement the Level 1, 2 and 3 BLAS. The communication library should provide the tool necessary for the implementation of numerical algorithms in linear algebra on distributed memory MIMD computers. The proposed routines can be found in the Appendix.

The “white paper” outlines a proposed set of linear algebra communication routines for the specification and manipulation of data structures that arise when linear algebra algorithms are implemented on distributed memory multicomputers. The scope of the BLACS is intentionally limited. This package is not to be viewed as a complete communication library for all applications. It is intended primarily for software developers and to a lesser extent for experienced applications programmers in the area of dense numerical linear algebra. We see these routines complementing the existing Level 1, 2, and 3 BLAS; providing tools for the implementation of numerical algorithms in linear algebra for distributed memory MIMD machines.

It is important to realize what kind of algorithms inspired the BLACS. They are being developed as part of our effort to implement a subset of the LAPACK library to distributed memory MIMD architectures. In implementing these routines, we intend to perform minimal changes to the algorithms and codes, as well as maintain portability of the final product. The codes are written in FORTRAN77 in the SPMD (Single Program Multiple Data) paradigm. So far, matrices have been mapped to nodes using (column) panel-wrapped storage, where a matrix is partitioned into panels of constant width that are wrapped onto the p nodes so that panels $p + ki$, $k=0, 1, \dots$ are assigned to processors with index $i - 1$.

One result of the above decision is that it suffices to implement broadcast and combine operations in a way that involves all nodes, i.e., the nodes form a one-dimensional array as far as global operations are concerned, although a more complicated network can be utilized to speed up the execution of such operations.

4 Proposed Language: Fortran D

Geoffrey Fox from Syracuse University and Chau-Wen Tseng from Rice University discussed Fortran D, a language for portable parallel processing. Fortran D is a version of Fortran extended

*The word “BLACS” was first used by Alan Edelman in describing a set of communication routines.

- There are both a high level and a low level set of communication primitives in the package.

Disadvantages:

- A restricted programming model is supported
 - No nonblocking send/receives
 - Only one process per processor
 - No synchronous interprocessor communication.
- Packing and unpacking of data is the users responsibility.

A few points were mentioned with respect to collecting trace data. Tracing can be dangerous unless the library is used correctly. The volume of trace data can easily overwhelm and the overhead can be substantial.

3.2 Zipcode

Tony Skjellum spoke on a package called Zipcode [6] which provides a portable communications library. Zipcode works on top of the Reactive Kernel/Cosmic Environment. The reactive Kernel/Cosmic Environment is a portable “light-weight” multi computer node operating system. The Reactive Kernel is implemented or emulated on the Intel iPSC/1, iPSC/2, iPSC/860, Symult S2010, and is emulated in shared memory computers such as the BBN TC2000 as well as networks of homogeneous NFS-connected workstations.

The key features of Zipcode are its design for extensibility, allowing the definition of many classes of communication and hence message receipt selectivity; support for abstraction of process lists into convenient working groups for communication; the ability to define many non-interfering communication contexts based on process lists with instantiation at runtime rather than compile-time; and the derivation of additional communication contexts through inheritance.

Skjellum provides a set of basic requirements for the BLACS:

- Support data-distribution-independent programming—applications define layout
- Provide logical 2D process grid abstraction
- Support global operations on logical 2D grids and subgrids
- Don’t interfere with or constrain other communication patterns of an application
- Recognize possibility of multiple logical process grids in an application
- Don’t interfere with MPMD programming
- Support application-defined pivoting and exploit communication pipelining

- The purpose of the BLAS and BLACS
- Their intended audience
- Criteria for inclusion
- View of the BLACS as software or specification
- Standardization of performance
- Testing and certification
- Conventions.

Jack Dongarra spoke on the development of LAPACK and the proposed extension to the project, the development of a core set of routines for distributed memory computers. The LAPACK project has generated approximately 500,000 lines of Fortran and in taking the package to distributed memory machines, software reuse is important. The LAPACK project [will be completed before the end of 1991, and the plan calls for a follow up project] [will address Fortran 90, C, distributed memory architectures, and trying to exploit IEEE arithmetic. Critical to the development of a distributed memory version of the linear algebra library is a portable/standard set of communication routines.

3 Existing Communication Libraries

3.1 PICL

Al Geist described a message passing interface for distributed memory parallel computer that was designed and in use at Oak Ridge National Laboratory called PICL (Portable Instrumented Communication Library) [4, 5]. The package is intended to aid in portable software development and to provide performance characterization through instrumentation and data visualization. The PICL package has been implemented on a number of platforms: Cogent, Intel iPSC/1, Intel iPSC/2, Intel iPSC/860, nCUBE, Symult S2010, Cosmic Environment, Linda, Unix System and X-Windows. The library is available in C and Fortran. The performance monitoring is provided through event-driven tracing capability. The routines in PICL produce time-stamped records of processor activities that serve as input to a visualization tool called ParaGraph also developed at Oak Ridge [4].

Some of the advantages of a package of this form are:

- A portable program can be designed by using the library.
- The overhead of using the library is minimal when compared to the native commands.
- Parameter values are checked for validity during runtime.
- The library is available in C and Fortran.
- Instrumentation can be provided automatically for performance and debugging monitoring.

LAPACK Working Note 34: Workshop on the BLACS

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February 6, 1992

Abstract: Forty-three people met on March 28, 1991, to discuss a set of Basic Linear Algebra Communication Subprograms (BLACS). This set of routines is motivated by the needs of distributed memory computers.

1 Introduction

This is an informal report of a workshop on the BLACS held in Houston on March 28, 1991. The workshop was organized by Jack Dongarra and attended by 43 people. Similar workshops were held in conjunction with the development of the Basic Linear Algebra Subprograms (BLAS). The purpose of the Houston workshop was to consider preliminary proposals for a set of basic communication routines used in library routines for solving problems in linear algebra.

The principle conclusions reached in this workshop were as follows:

- a) The motivation for the BLACS is to increase portability, efficiency and modularity at a high level.
- b) The audience for the BLACS are mathematical software experts and people with large scale scientific computations to perform
- c) A systematic effort must be made to achieve a *de facto* standard for the BLACS. Further discussion would take place in the Fall 1991 at Cornell.
- d) The discussion opened the possibility of a higher level of expressing than reflected in the "white paper".

2 General Issues Related to the BLACS

Richard Hanson discussed general issues he felt should be borne in mind when defining the BLACS. The issues fell under a number of headings and follow a report by David Dods on and John Lewis published in SIGNUM[3].

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