Parallel Numerical Linear Algebra for Future Extreme-Scale Systems

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"Future and emerging technologies shall support collaborative research in order to extend Europe’s capacity for advanced and paradigm-changing innovation. It shall foster scientific collaboration across disciplines on radically new, high-risk ideas and accelerate development of the most promising emerging areas of science and technology as well as the Union wide structuring of the corresponding scientific communities."

COMMISSION PROPOSAL ON ESTABLISHING HORIZON 2020 - THE FRAMEWORK PROGRAMME FOR RESEARCH AND INNOVATION (2014-2020)
Towards Exascale High Performance Computing

Aim of the Horizon 2020 FETHPC call:

*Attract projects that can achieve world-class extreme scale computing capabilities in platforms, technologies and applications*

19 Research and Innovation Actions (RIA); 2 Coordination and Support Actions (CSA)
Figure: NLAFET (Umeå Univ., 3.9MEUR), ExaFLOW (KTH, 3.3MEUR), and EuroLab4HPC (Chalmers, 1.5MEUR)
Members of the NLAFET Consortium

- Umeå University, Sweden (UMU; Coordinator Bo Kågström; Lennart Edblom)
- The University of Manchester, UK (UNIMAN; Jack Dongarra)
- Institute National de Recherche en Informatique et en Automatique, France (INRIA; Laura Grigori)
- Science and Technology Facilities Council, UK (STFC; Iain Duff)

Key European players with recognized leadership, proven expertise, experience, and skills across the scientific areas of NLAFET!

Vast experience contributing to open source projects!
NLAFET—Aim and Main Research Objectives

Aim: *Enable a radical improvement in the performance and scalability of a wide range of real-world applications relying on linear algebra software for future extreme-scale systems.*

- Development of novel *architecture-aware algorithms* that expose as much parallelism as possible, exploit heterogeneity, avoid communication bottlenecks, respond to escalating fault rates, and help meet emerging power constraints
- Exploration of *advanced scheduling strategies and runtime systems* focusing on the extreme scale and strong scalability in multi/many-core and hybrid environments
- Design and evaluation of novel strategies and software support for both *offline and online auto-tuning*
- Results will appear in the open source *NLAFET software library*
WP1: Management and coordination

WP5: Challenging applications—a selection
Materials science, power systems, study of energy solutions, and data analysis in astrophysics

WP7: Dissemination and community outreach
Research and validation results; stakeholder communities
Research focus—Critical set of NLA operations

- WP2: Dense linear systems and eigenvalue problem solvers
- WP3: Direct solution of sparse linear systems
- WP4: Communication-optimal algorithms for iterative methods
- WP6: Cross-cutting issues

WP2, WP3 and WP4: research into extreme-scale parallel algorithms
WP6: research into methods for solving common cross-cutting issues
WP2, WP3 and WP4 at a glance!

- Linear Systems Solvers
- Hybrid (Batched) BLAS
- Eigenvalue Problem Solvers
- Singular Value Decomposition Algorithms
- Lower Bounds on Communication for Sparse Matrices
- Direct Methods for (Near–)Symmetric Systems
- Direct Methods for Highly Unsymmetric Systems
- Hybrid Direct–Iterative Methods
- Computational Kernels for Preconditioned Iterative Methods
- Iterative Methods: use $p$ vectors per it, nearest-neighbor comm
- Preconditioners: multi-level, comm. reducing
Why avoid communication?

Algorithms have two costs (measured in time or energy):

1. Arithmetic (FLOPS)
2. Communication: moving data between
   - levels of a memory hierarchy (sequential case)
   - processors over a network (parallel case).

*Extreme scale systems accentuate the need to avoid communication!*
Why avoid communication?

Running time of an algorithm involve three terms:

- # Flops \( \times \) Time per flop
- # Words moved / Bandwidth
- # Messages \( \times \) Latency

\[
\text{Time per flop } \ll \frac{1}{\text{Bandwidth}} \ll \text{Latency}
\]

Gaps growing exponential with time [FOSC]

<table>
<thead>
<tr>
<th>Annual improvements</th>
<th>Time per flop</th>
<th>Bandwidth</th>
<th>Latency</th>
</tr>
</thead>
<tbody>
<tr>
<td>59%</td>
<td>Network</td>
<td>26%</td>
<td>15%</td>
</tr>
<tr>
<td>DRAM</td>
<td>23%</td>
<td>5%</td>
<td></td>
</tr>
</tbody>
</table>

Goal: Redesign algorithms (or invent new) to avoid communication!  
*Attain lower bounds on communication if possible!*
Batched BLAS motivation

Accelerators coprocessors, like GPUs, support high levels of parallelism.

Can achieve very high performance for large data parallel computations if CPU handles computations on critical path.

Currently, not the case for applications that involve large amounts of data that come in small units.

Figure: Memory hierarchy of a heterogeneous system from the point of view of a CUDA core of an NVIDIA K40c GPU with 2,880 CUDA cores.
Batched BLAS

Multiple independent BLAS operations on small matrices grouped together as a single routine

**Sample applications:** Structural mechanics, Astrophysics, Direct sparse solvers, High-order FEM simulations
WP6: Cross-cutting issues and challenges!

**Extreme-scale systems are hierarchical and heterogeneous in nature!**

- **Scheduling and Runtime Systems:**
  - Task-graph-based multi-level scheduler for multi-level parallelism
  - Investigate user-guided schedulers: application-dependent balance between locality, concurrency, and scheduling overhead
  - Run-time system based on parallelizing critical tasks \((Ax = \lambda Bx)\)
  - Address the thread-to-core mapping problem

- **Auto-Tuning:**
  - **Off-line**: tuning of critical numerical kernels across hybrid systems
  - **Run-time**: use feedback during and/or between executions on similar problems to tune in later stages of the algorithm

- **Algorithm-Based Fault Tolerance:**
  - Explore new NLA methods of resilience and develop algorithms with these capabilities.
Task-graph based scheduling and run-time systems

- Express algorithmic dataflow, not explicit data movement
- Blocked Cholesky tasks: POTRF, TRSM, GEMM, SYRK
- PTG representation: symbolic, problem size independent
Task-graph based scheduling and run-time system

- Data flow based execution using PaRSEC (ICL-UTK)
- Assigns computations threads to cores; overlaps comm. & comp.
- Distributed dynamic scheduler based on NUMA nodes and data reuse

Figure: Cholesky PTG run by PaRSEC; 45% improvement
Generalized eigenvalue problem

Find pairs of eigenvalues $\lambda$ and eigenvectors $x$ s.t.

$$Ax = \lambda Bx$$

1. QR factorization
2. Hessenberg-Triangular reduction
3. QZ algorithm (generalized Schur decomposition)
Motivating (terrifying) example

**Tunable parameters in state-of-the-art parallel QZ algorithm:**

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>$n_{\text{min1}}$</td>
<td>Algorithm selection threshold.</td>
</tr>
<tr>
<td>$n_{\text{min2}}$</td>
<td>Algorithm selection threshold.</td>
</tr>
<tr>
<td>$n_{\text{min3}}$</td>
<td>Parallelization threshold.</td>
</tr>
<tr>
<td>$P _{\text{AED}}$</td>
<td>Number of processors for subproblems.</td>
</tr>
<tr>
<td>MMULT</td>
<td>Level-3 BLAS threshold.</td>
</tr>
<tr>
<td>NCB</td>
<td>Cache-blocking block size.</td>
</tr>
<tr>
<td>NIBBLE</td>
<td>Loop break threshold.</td>
</tr>
<tr>
<td>$n_{\text{AED}}$</td>
<td>Deflation window size.</td>
</tr>
<tr>
<td>$n_{\text{shift}}$</td>
<td>Number of shifts per iteration.</td>
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<tr>
<td>NUMWIN</td>
<td>Number of windows.</td>
</tr>
<tr>
<td>WINEIG</td>
<td>Eigenvalues per window.</td>
</tr>
<tr>
<td>WINSIZE</td>
<td>Window size.</td>
</tr>
<tr>
<td>WNEICR</td>
<td>Number of eigenvalues moved together.</td>
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WP5: Challenging applications—a selection

- **Dense solvers/eigensolvers in materials science and chemistry**
  - Thomas Schulthess, ETH Zurich, Switzerland
  - $Ax = \lambda Bx$, $A$ Hermitian dense, $B$ Hermitian positive definite

- **Load flow based calculations in large-scale power systems**
  - Bernd Klöss, DlgsILENT GmbH, Germany
  - Extreme scale, highly sparse, unsymmetrical and very ill-conditioned $Ax = b$

- **Energy solutions and Code Saturne**
  - Yvan Fournier, EDF, France
  - Communication-avoiding methods for sparse linear systems

- **Data analysis in astrophysics and the Midapack library**
  - Radoslaw Stompor, University Paris 7, France; Carlo Baccigalupi, SISSA Italy
  - Communication-avoiding methods adapted to generalized least-squares problem
NLAFET Summary

- Deliver a new generation of computational tools and software for problems in numerical linear algebra with a focus on extreme-scale systems
- **Linear algebra** is both fundamental and ubiquitous in computational science and its vast application areas
- **Co-design effort** for designing, prototyping, and deploying new NLA software libraries:
  - Exploration of new algorithms
  - Investigation of advanced scheduling strategies
  - Investigation of advanced auto-tuning strategies
  - Open source
- Stakeholder collaborations (users, academia, HW and SW vendors)