

Cost and Utility Trade-offs on IaaS Clouds, Grids, and On-Premise Clusters

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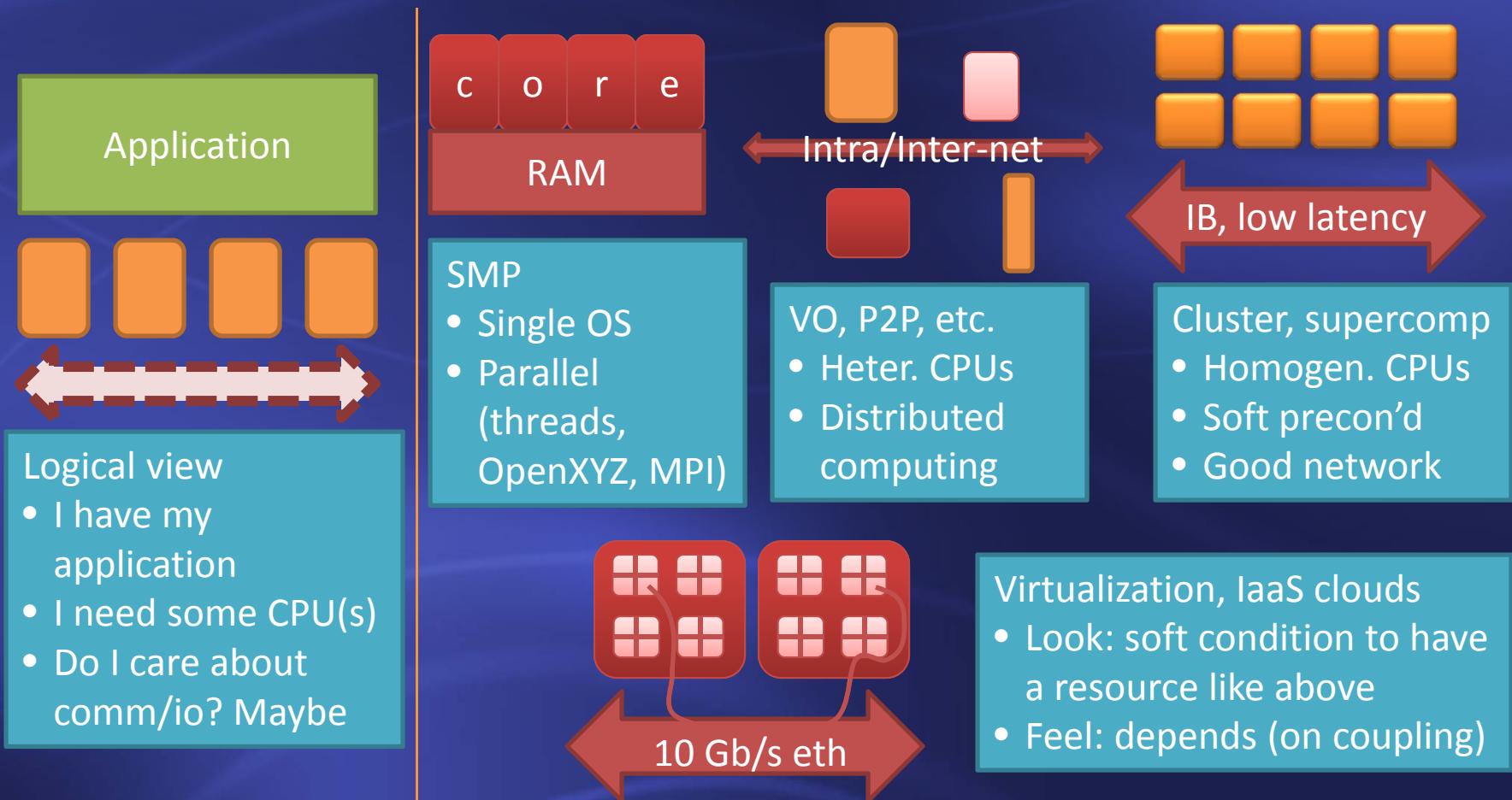


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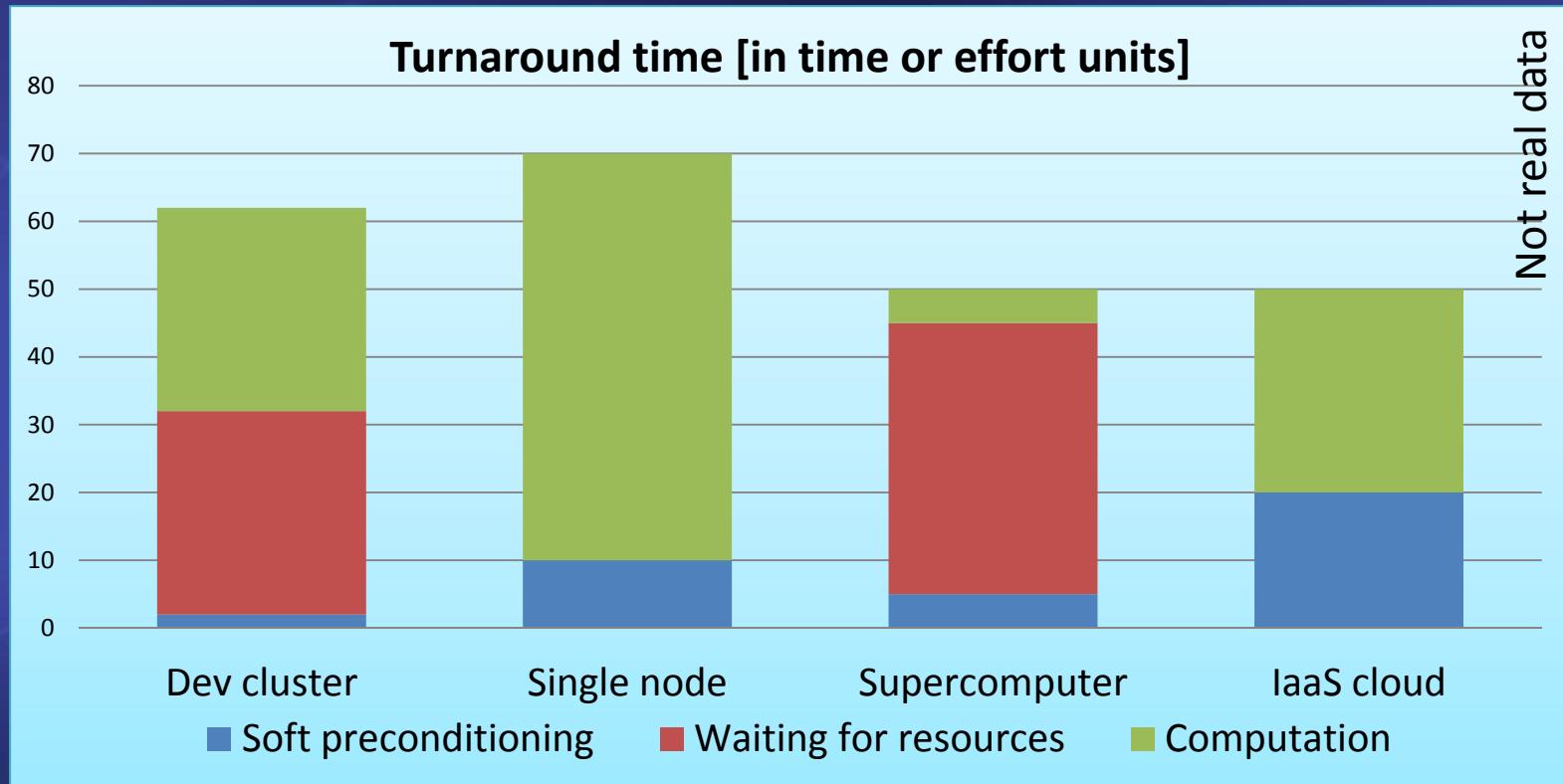
Resource heterogeneity

- Equivalent platforms for unmodified application



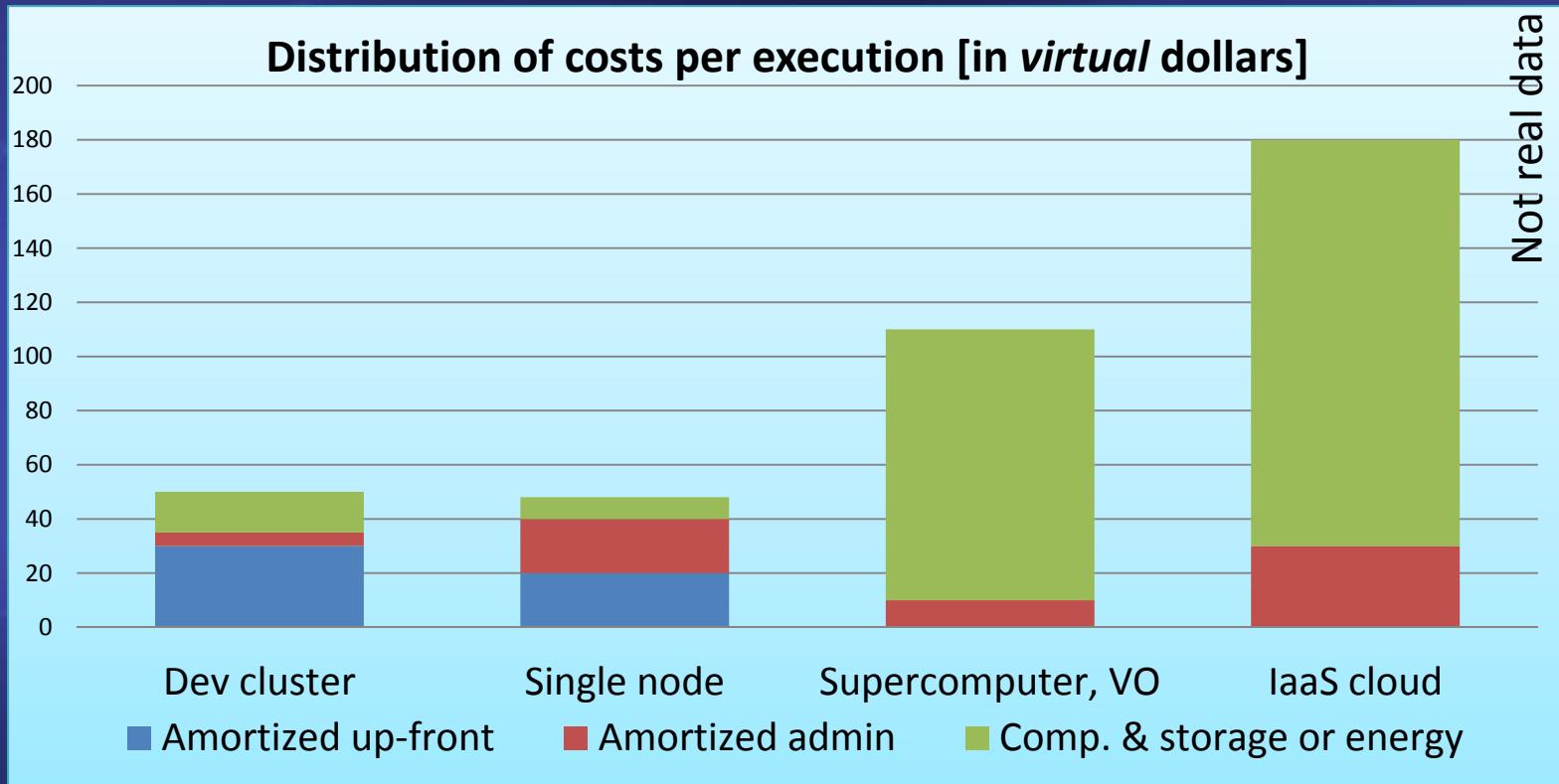
Trade-offs: (1) utilization

- If different computational platforms may be used interchangeably ...



Trade-offs: (2) costs

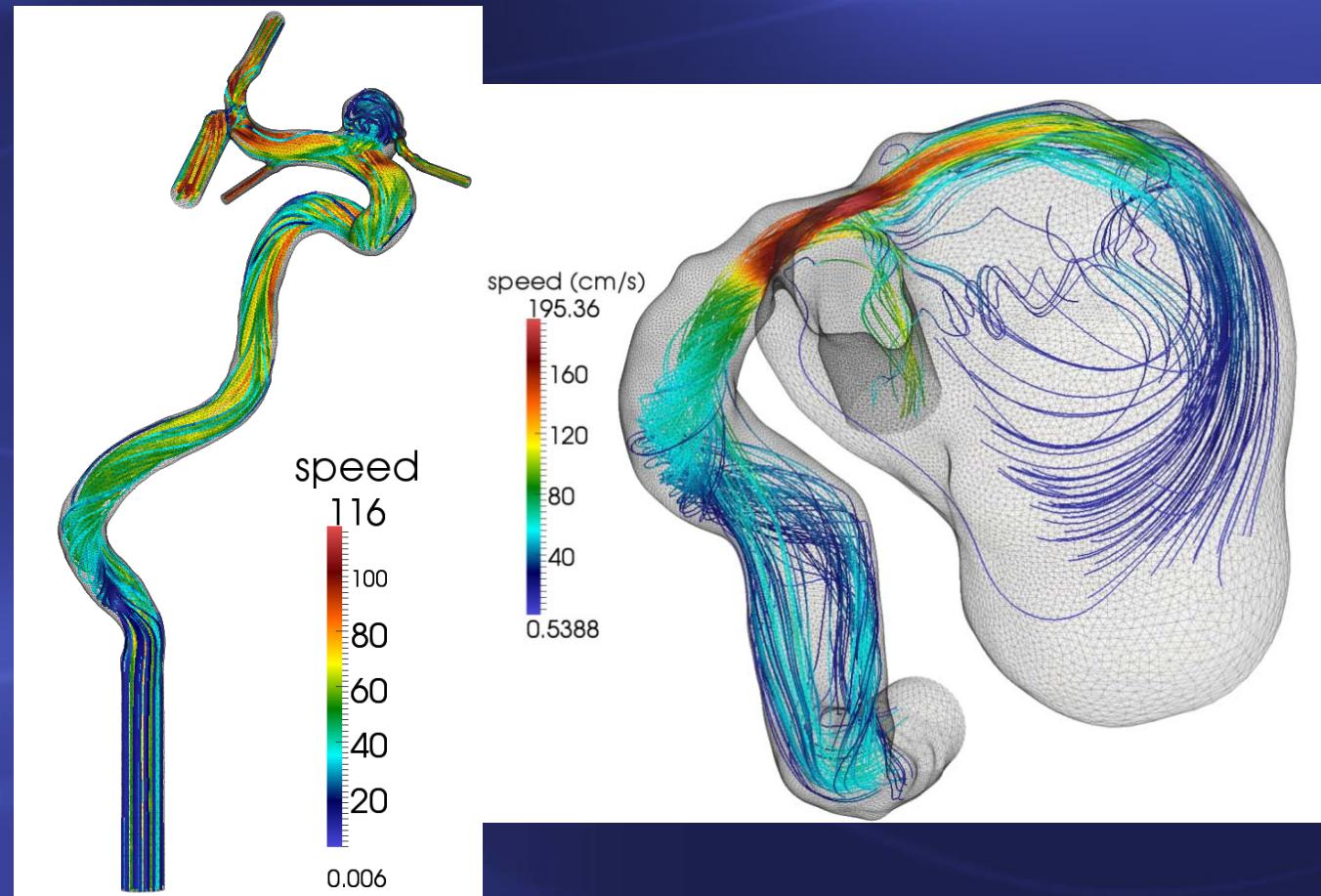
- Dev environment – no soft conditioning
- “Rented” resources – no up-front costs



Use-case

Case study: LifeV-based hemodynamic simulation

- CFD/FEM MPI parallel code
- LifeV library
- Issues
 - Process placement
 - Turnaround
 - Cost
- Utility



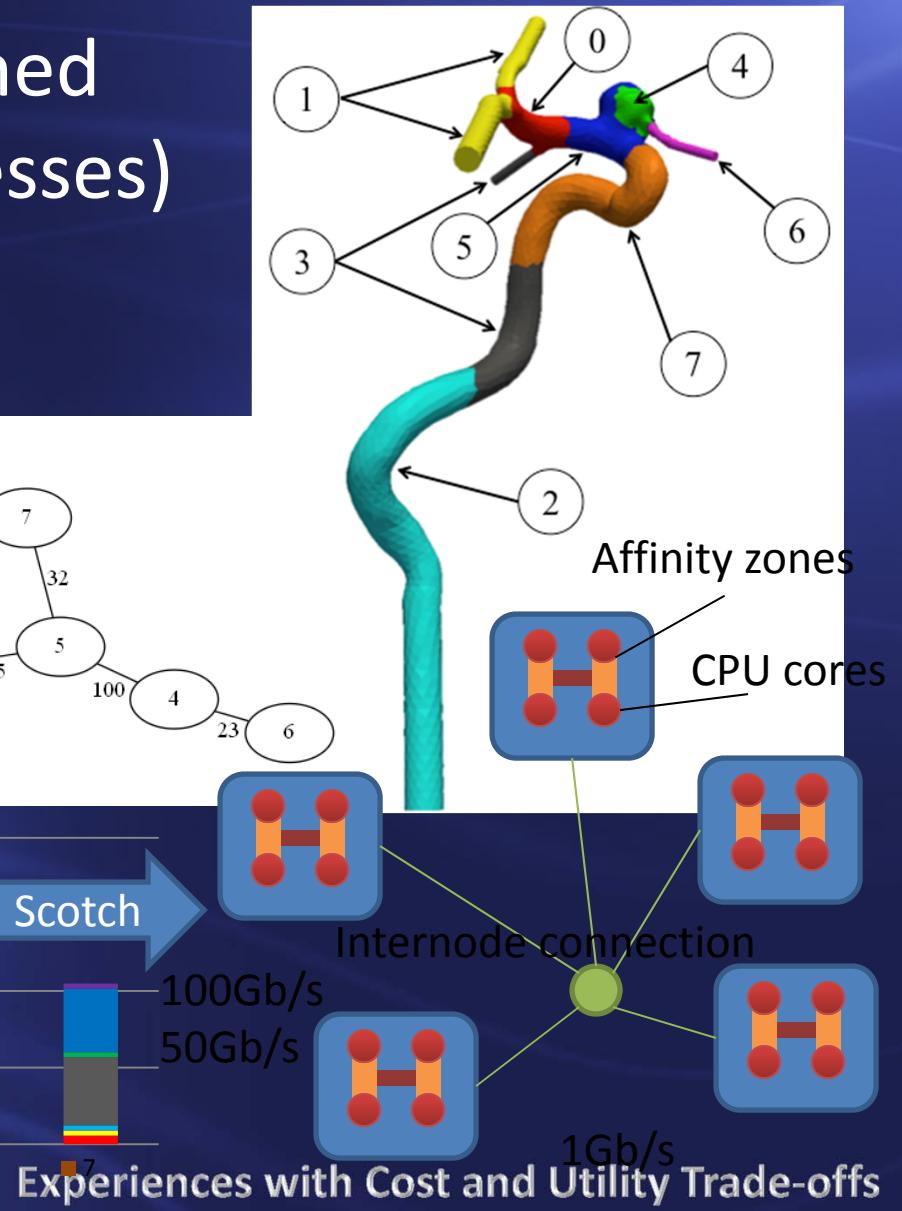
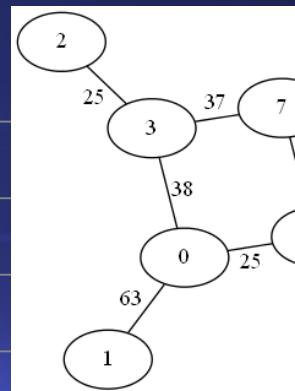
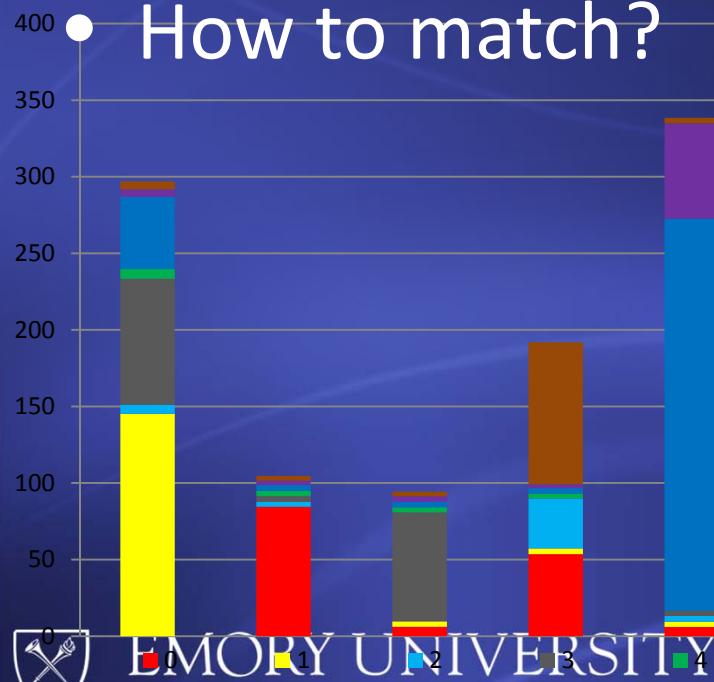
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Experiences with Cost and Utility Trade-offs

Communication patterns

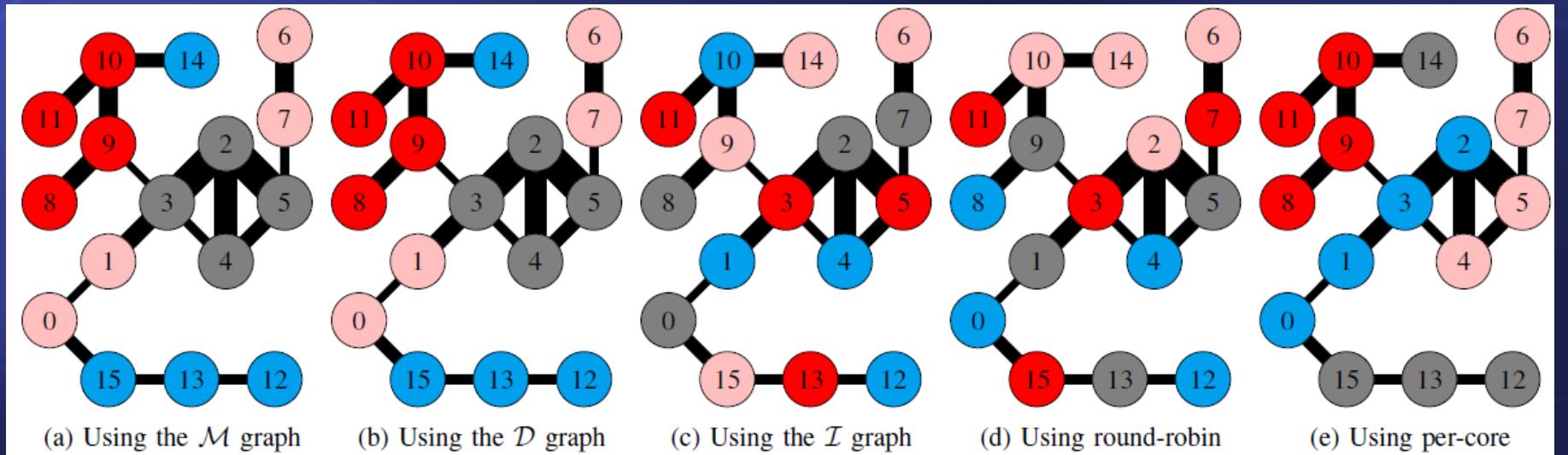
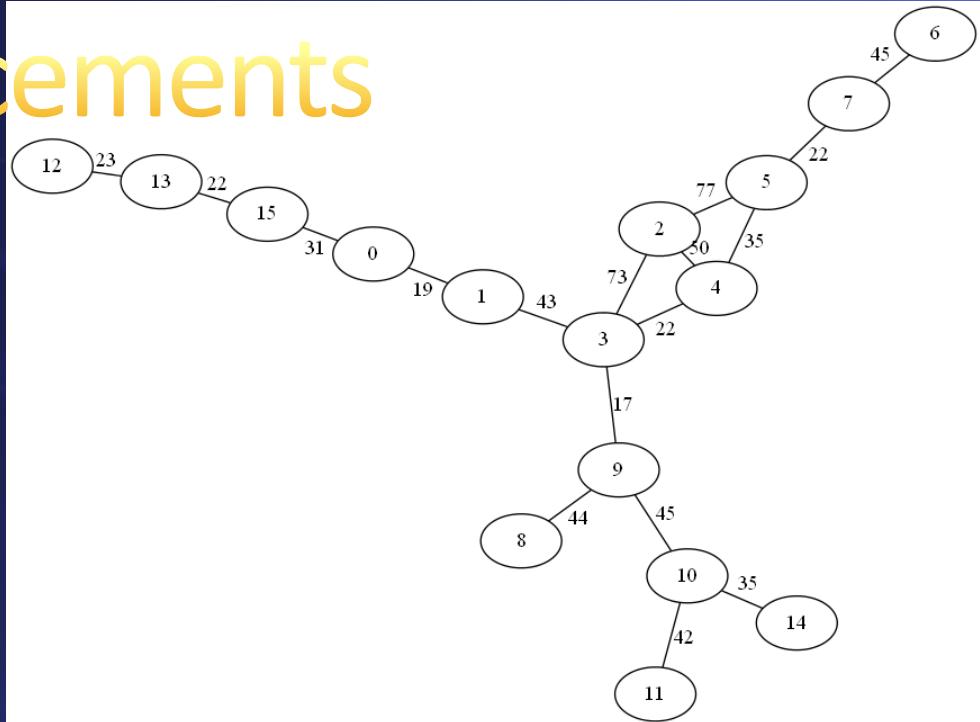
- FEM input mesh partitioned into 8 partitions (8 processes)
- Logical topology graph
- Physical topology

• How to match?



4core node placements

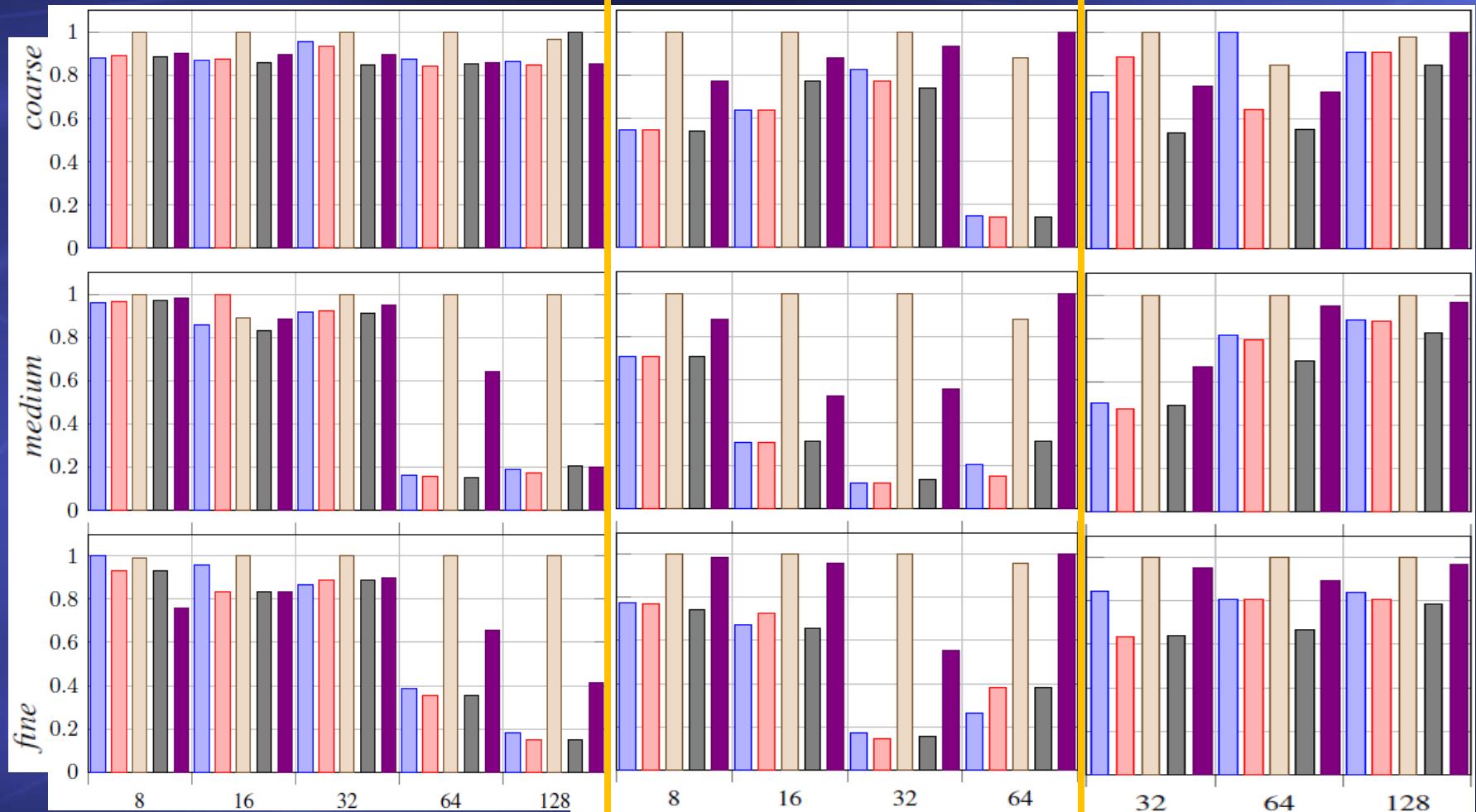
- M – data from the partitioner
- D – data from benchmarks
- I – inverted D
- Round-robin and per-core
 - input-agnostic allocation



cluster

now

ec2



NP



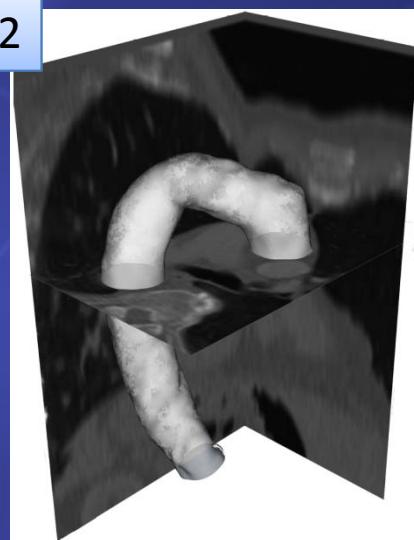
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data part invert pcore rr

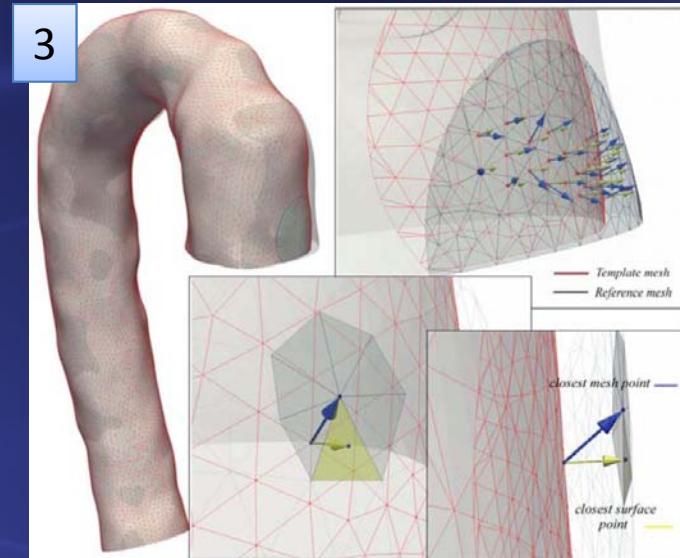
Experiences with Cost and Utility Trade-offs



Hemodynamics in the Clinic

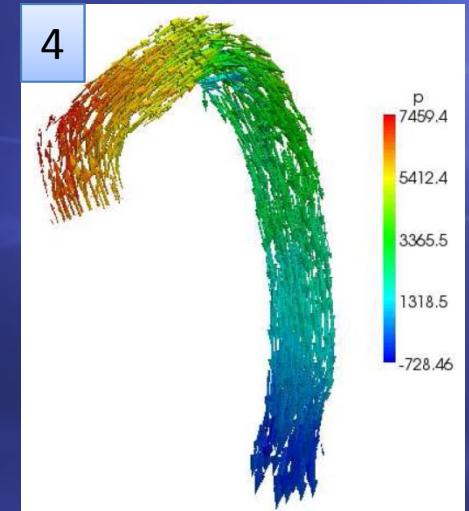


Reconstruction
from Computed
Tomography

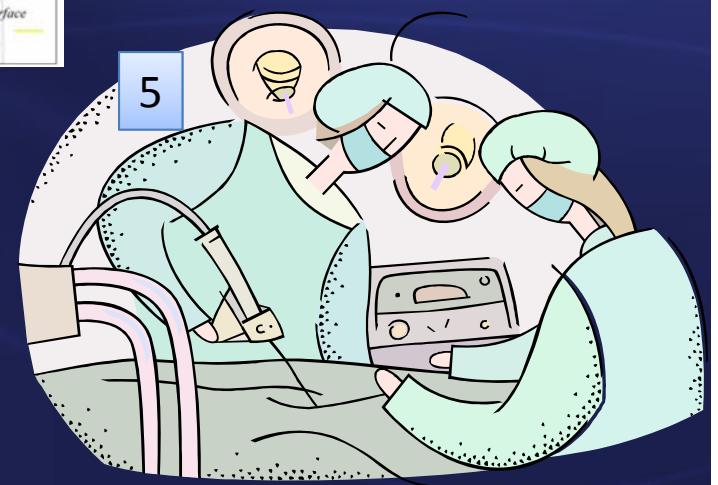


Digitalization,
mesh generation

- Diagnosis
- Bypass or stent placement
- ***Cost vs. turnaround***



Solution (velocity
vectors and pressure)



Surgery

Experiences with Cost and Utility Trade-offs



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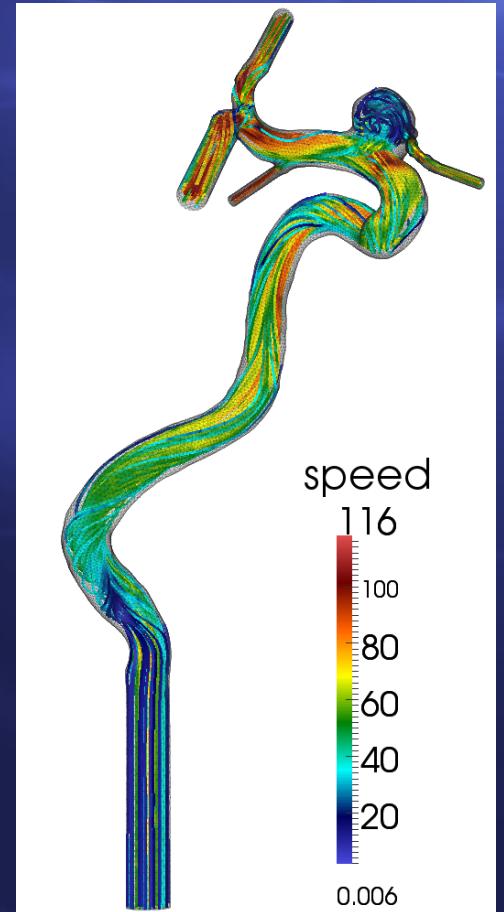
Trade-off experiment setting

1. Ellipse: university cluster
256-node 1k-core; 1Gb/s ethernet; queue SGE
2. Puma: dev environment cluster
32-nodes 128-core; IB SDR; queue PBS
3. Lonestar: XSEDE supercomputer
IB QDR; queue PBS
4. Rockhopper cluster: On-Demand HPC Cloud Service, Penguin Computing
IB QDR; queue PBS
5. Amazon EC2; 1-16 nodes
cc2.8xlarge 16-core per node; 10Gb/s ethernet



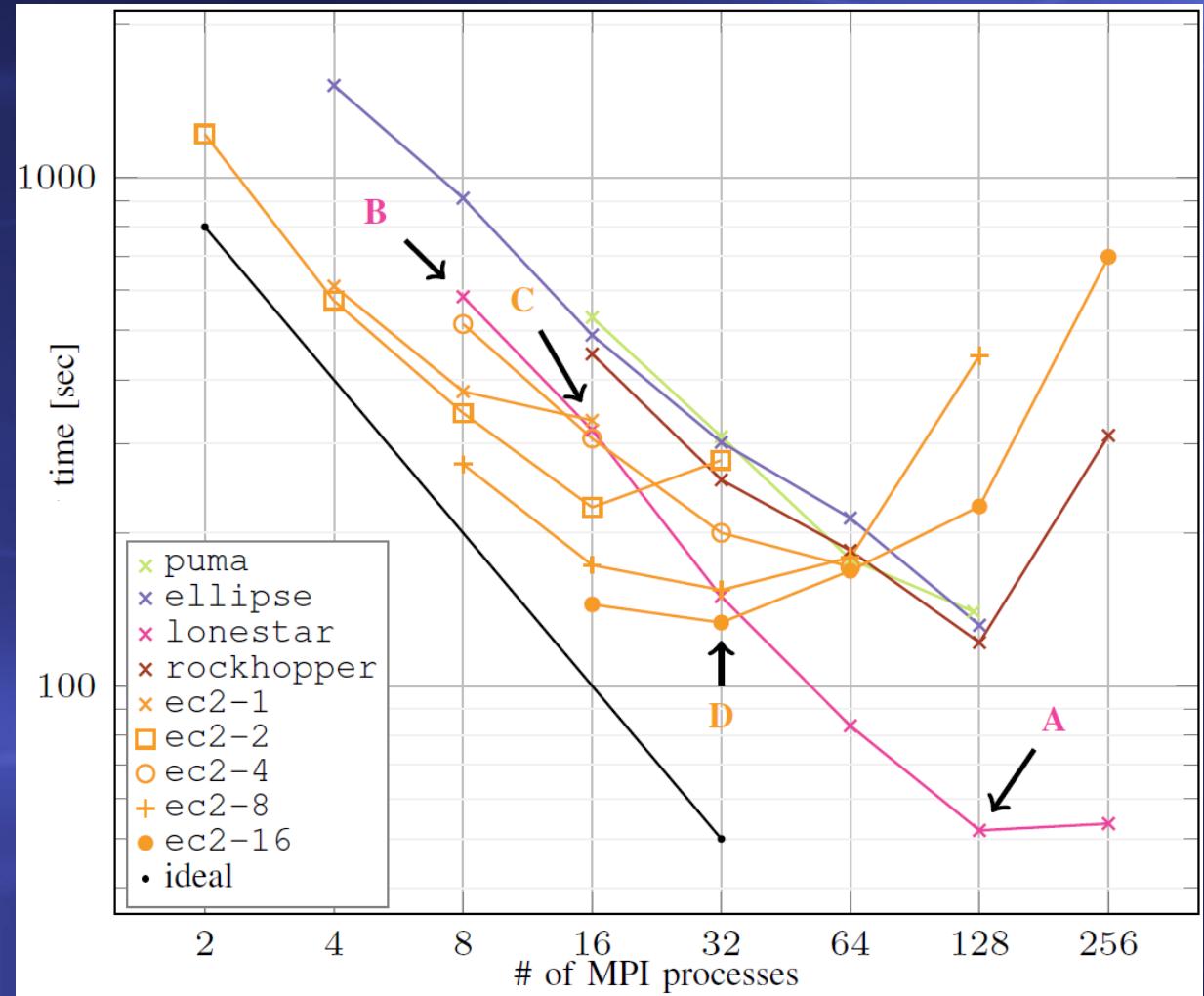
Application

- Aneurism simulation
- About 1 million elements (FEM)
- Computes pressure and velocity for each 0.01 sec
- Same problem, various number of processes (strong scalability test)
- One MPI process per computing core in round-robin placement



Cost of computation

- A – fastest overall
- B – supercomputer nodes are not the fastest
- C – single EC2 = 16 processes on supercomputer
- D – fastest EC2 configuration
- EC2 scalability...



Fastest time on each platforms

Single simulation frame time (proxy)

rank	time to completion [s]	target	# of MPI proc.
1	1h 31m	lonestar	128
2	3h 33m	rockhopper	128
3	3h 50m	ellipse	128
4	3h 53m	ec2-16	32
5	4h 05m	puma	124
6	4h 30m	ec2-8	32
7	5h 00m	ec2-4	64
8	6h 33m	ec2-2	16
9	9h 43m	ec2-1	16

Slowest time = 6.4 x
fastest. **Avg is 4h 44m**

Our dev
machine



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Expenditure calculation

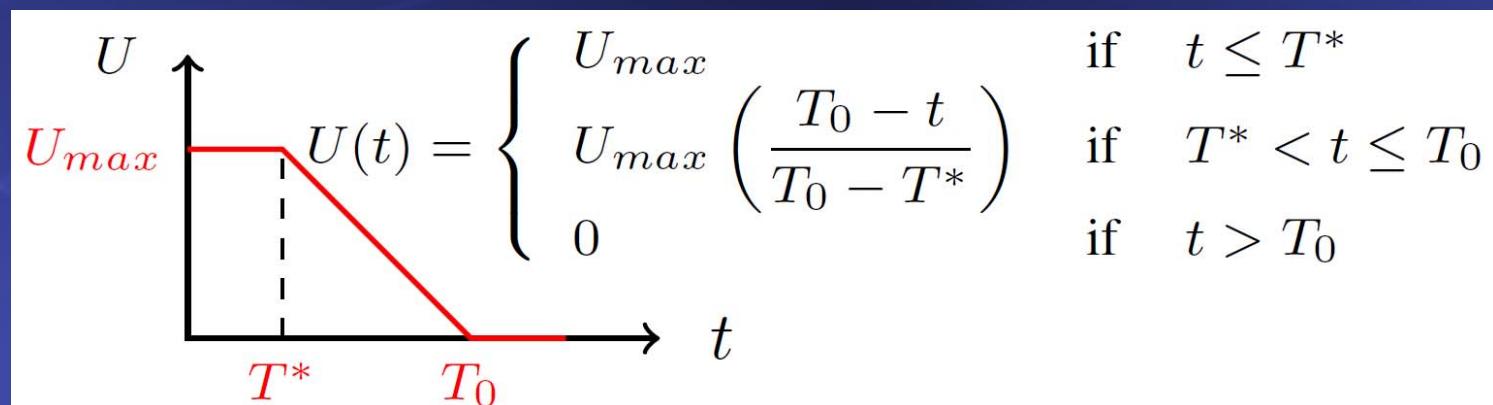
- Puma and Lonestar – estimated cost based on hardware/operational expenses; typical figures reported in literature
- Ellipse – university pricing
- Rockhopper – actual charges
- EC2 – we used as many cheap spot-request (bid-based) instances as possible (about 6 times cheaper than regular instances)

target	cost per core-hour
puma	2.3¢
ellipse	3¢
lonestar	7¢
rockhopper	10¢
ec2	2.27-15¢



Utility function

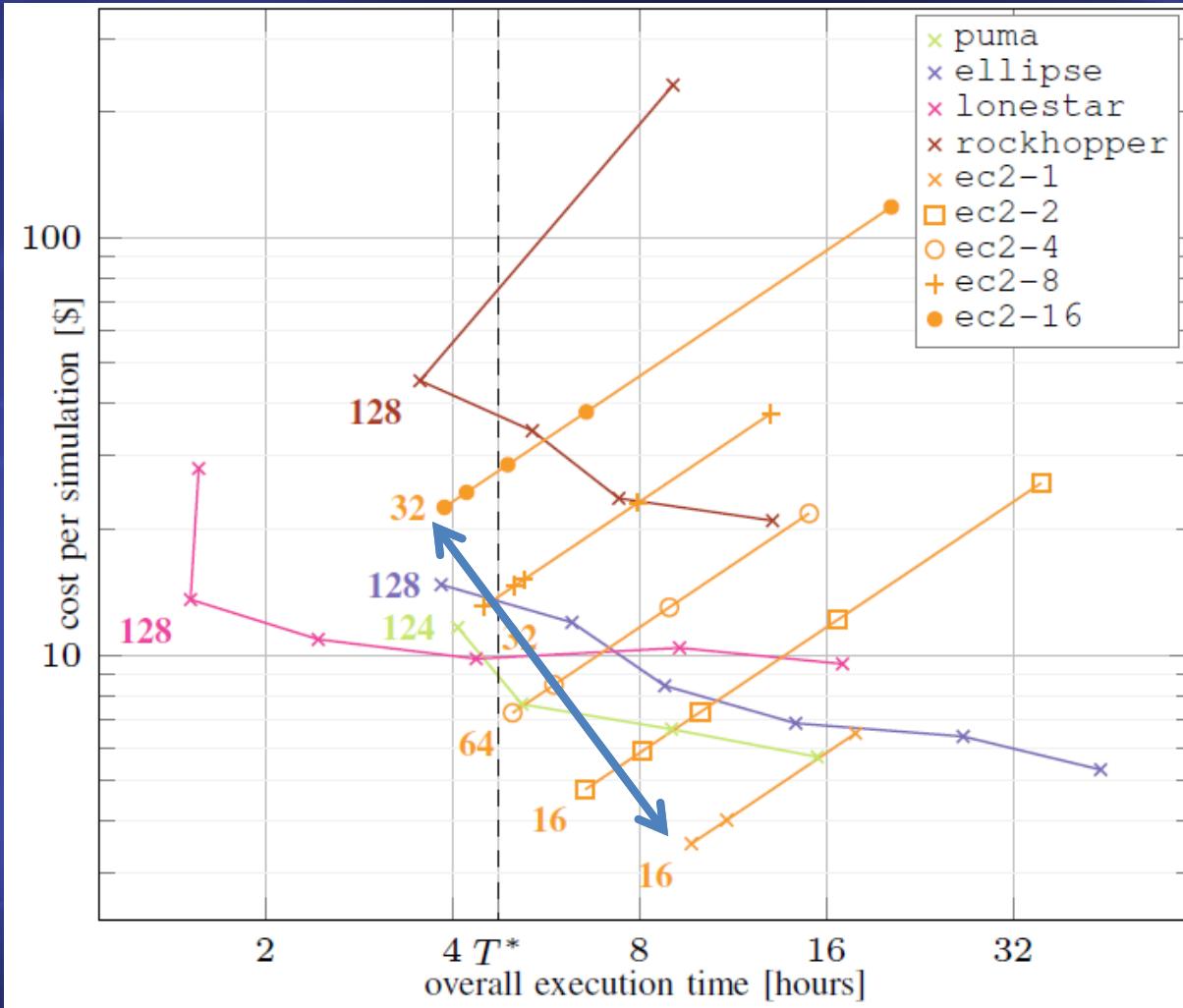
- Value of simulation results to user over time



- U – utility value (e.g., in \$)
- U_{max} – the max value the user is willing to pay (importance of the task)
- T^* - expected completion time
- $|T^* - T_0|$ - delay tolerance
- T_0 – latest completion time



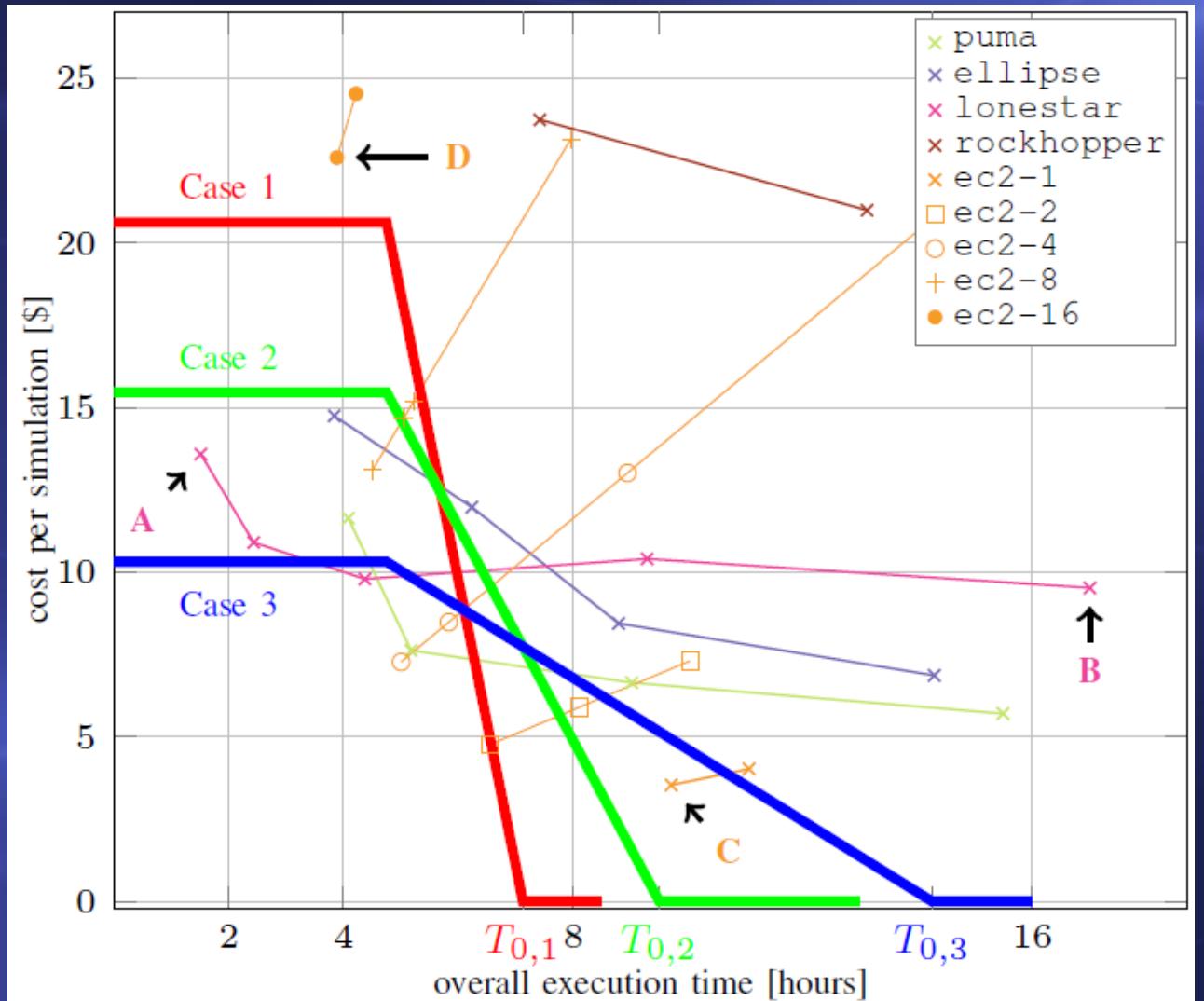
Relation between time and cost



Low (3), high (1),
average (2)
priority jobs
 $T^* = 4.44$ hrs
 $\#3 = \$10.31$
 $\#1 = \$20.62$

A – overall
fastest execution
C – overall
cheapest
execution
D – fastest time
for EC2

Results



Conclusions and future work

- Turnaround vs. cost tradeoffs vary considerably across platforms (multiplied by parameter sweeps)
- Some IaaS cloud resources offer superior capabilities compared to cluster/supercomputer nodes (large single instances vs. local clusters)
- Queue waiting time is not considered in this study, but it may significantly change selection decisions for time-critical computation (e.g., medical diagnosis)

